# Sanjeev J. Koppal

Office: NEB 437 Email: sjkoppal@ece.ufl.edu

*Ph: 352-392-8942 Lab page:* focus.ece.ufl.edu

## EXPERIENCE AND EDUCATION

| Associate Professor (IEEE and Optica Senior Member)<br>University of Florida, Electrical and Computer Engineering<br>Director of the Florida Optics and Computational Sensor (FOCUS) Lab | 2021-present |
|--|--------------|
| Amazon Scholar<br>Amazon Robotics  | 2022-present |
| <b>Assistant Professor</b><br>University of Florida, Electrical and Computer Engineering   | 2014-2021    |
| <b>Member of Technical Staff</b><br>Texas Instruments Imaging R&D Group  | 2012-2014    |
| <b>Post-doctoral Research Associate</b><br><i>Harvard University</i><br>Mentor: Prof. Todd Zickler   | 2009-2012    |
| Graduate Research Assistant<br>Robotics Institute, Carnegie Mellon University<br>Ph.D. Robotics Aug 2009<br>Advisor: Prof. Srinivasa Narasimhan  | 2003-2009    |
| Undergraduate Research Assistant<br>University of Southern California<br>B.S. Computer Science May 2003<br>Mentor: Prof. Gaurav Sukhatme   | 1999-2003    |

## AWARDS

UF ECE Department Teaching Award (2024) Linda and Kent Fuchs Faculty Fellow (2023-present) UF Term Professorship (2021-24) ONR Summer Faculty Fellow <sup>1</sup> (2021) NSF CAREER Award (2020) Best Paper Award Finalist (CVPR 2019) Best Student Paper Award (NEMS 2018) Best Student Paper Award (ECCV 2016) Outstanding Reviewer Award (ECCV 2016) USC Computer Science Award for Outstanding Achievement (2003) USC Trustee Scholarship (full tuition) (1999-2003)

 $<sup>^1\</sup>mathrm{Cancelled}$  due to COVID-19

#### **JOURNALS**

 ${\bf J26}$  Design of an Adaptive Lightweight LiDAR to Decouple Robot-Camera Geometry IEEE Transactions on Robotics, 2024

Yuyang Chen, Dingkang Wang, Lenworth Thomas, Karthik Dantu, S. J. Koppal

**J25** HyperPRI: A dataset of hyperspectral images for underground plant root study Computers and Electronics in Agriculture, 2024

Spencer J. Chang, Ritesh Chowdhry, Yangyang Song, T. Mejia, A. Hampton, Shelby Kucharski, T.M. Sazzad, Y. Zhang, **S. J. Koppal**, Chris H. Wilson, Stefan Gerber, Barry Tillman, Marcio F.R. Resende, William M. Hammond, Alina Zare

**J24** Hyperspectral Signals in the Soil: Plant-soil Hydraulic Connection and Disequilibrium as Mechanisms of Drought Tolerance and Rapid Recovery Plant, Cell and Environment, 2024

Yangyang Song, Gerard Sapes, Spencer Chang, Ritesh Chowdhry, Tomas Mejia, Anna Hampton, Shelby Kucharski, Shahiar Sazzad TM; Yuxuan Zhang; Barry L. Tillman, Márcio Resende F R, **S. J. Koppal**, Chris Wilson, Stefan Gerber, Alina Zare, William Hammond

J23 Event-based Dual Photography for Transparent Scene Reconstruction Optics Letters 2023Xiaomeng Liu, Joshua D. Rego, Suren Jayasuriya, S. J. Koppal

**J22** Dense Lissajous Sampling and Interpolation for Dynamic Light-Transport Optics Express 2021 X. Liu, K. Henderson, J. Rego, S. Jayasuriya and S. J. Koppal

J21 A Miniature LiDAR with a Detached MEMS Scanner for Micro-robotics IEEE Sensors Journal 2021D. Wang, H. Xie, L. Thomas and S. J. Koppal

J20 Fast Foveating Cameras for Dense Adaptive Resolution
IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI), 2021
B. Tilmon, E. Jain, S. Ferrari and S. J. Koppal

J19 Adaptive Fovea for Scanning Depth SensorsInternational Journal of Robotics Research, 2020Z. Tasneem, C. Adhivarahan, D. Wang, H. Xie, K. Dantu and S. J. Koppal

J18 Design and Calibration of a Fast Flying-Dot Projector
for Dynamic Light Transport Acquisition
Transactions on Computational Imaging, 2020
K. Henderson, X. Liu, J. Folden, B. Tilmon, S. Jayasuriya and S. J. Koppal

J17 Proximity-based Sensor Fusion of Depth Cameras and Isotropic Rad-detectors
Transactions on Nuclear Science, 2020
K. Henderson, X. Liu, K. Stadnakia, A. Martin, A. Enqvist and S. J. Koppal

J16 A low-voltage, low-current, digital-driven MEMS mirror for low-power LiDAR IEEE Sensors Letters, 2020D. Wang, L. Thomas, S. J. Koppal, Y. Ding and H. Xie

J15 A Monolithic Forward-View MEMS Laser Scanner With Decoupled Raster Scanning and Enlarged Scanning Angle for Micro LiDAR Applications
Journal of Microelectromechanical Systems, 2020
D. Wang, S. J. Koppal and H. Xie

J14 The Security-Utility Trade-off for Iris Authentication and Eye Animation for Social Virtual Avatars
IEEE VR 2020 (in the proceedings of TVCG 2020)
B. John, S. Joerg, S. J. Koppal and E. Jain

J13 A Silicon Optical Bench with Vertically-oriented Micromirrors for Active Beam Steering
Sensors and Actuators A: Physical, 2019
D Wang, C Watkins, S. J. Koppal and H Xie

J12 Data Fusion for a Vision-Aided Radiological Detection System:
Calibration Algorithm Performance
Nuclear Instruments and Methods in Physics A, 2018
K. Stadnikia, K. Henderson, A. Martin, P. Riley, S. J. Koppal and Andreas Enqvist

J11 Focal Flow: Velocity and Depth from Differential Defocus through Motion International Journal on Computer Vision (IJCV), 2017
E. Alexander, Q. Guo, S. J. Koppal, S.J. Gortler, and T. Zickler

J10 Leveraging gaze data for segmentation and effects on comics
Transactions on Multimedia Computing (TOMM), 2017
I. Thirunarayanan, K. Khetarpal, S. J. Koppal, O. LeMeur, J. Shea and E. Jain

**J09** Pre–capture privacy for small vision sensors Transactions on Pattern Analysis and Machine Intelligence (PAMI) 2016 F. Pittaluga and **S. J. Koppal** 

J08 A survey on computational photography in the small IEEE Signal Processing Magazine, 2016S. J. Koppal

J07 Wide-angle structured light with a scanning MEMS mirror in liquid Optics Express, 2016X. Zhang, S. J. Koppal, R. Zhang, L. Zhou, E. Butler and H. Xie

J06 Beyond perspective dual photography with illumination masksTransactions on Image Processing (TIP), 2015S. J. Koppal and S. G. Narasimhan

J05 Generalized assorted camera arrays: robust cross-channel registration and applic.Transactions on Image Processing (TIP), 2015J. Holloway and K. Mitra and S. J. Koppal and A. Veeraraghavan

J04 Towards wide-angle micro vision sensors
Transactions on Pattern Analysis and Machine Intelligence (PAMI), 2013
S. J. Koppal, I. Gkioulekas, T. Young, H. Park, K. Crozier, G. Barrows and T. Zickler

J03 Exploiting DLP illumination dithering for reconstruction and photography of high-speed scenes
International Journal on Computer Vision (IJCV), 2011.
S. J. Koppal, S. Yamazaki and S. G. Narasimhan

J02 A viewer-centric editor for stereoscopic cinema
IEEE Computer Graphics and Applications (CG&A), 2011.
S. J. Koppal, L. Zitnick, M. Cohen, S. Kang, B. Ressler and A. Colburn

J01 Appearance derivatives for iso-normal clustering of scenesTransactions on Pattern Analysis and Machine Intelligence (PAMI), 2008.S. J. Koppal and S. G. Narasimhan

## **CONFERENCES**

C37 FoveaCam++: Systems-Level Advances for Long Range Multi-Object High-Resolution Tracking IROS 2024 Yuxuan Zhang and S. J. Koppal

C36 Confocal Bistatic LIDAR in Scattering Media SPIE Defense + Commercial Sensing 2024 J. Folden, D. Alley, D. Illig, L. Mullen and S. J. Koppal

C35 Demystifying Edge Cases in Advanced IC Packaging Inspection through Novel Explainable AI Metrics
ECTC 2024
S. Ghosh, A. Roy, M. Al Hasan Md, P. Craig, N. Varshney, S. J. Koppal and N. Asadizanjani

C34 Schrödinger's Camera: First Steps Towards a Quantum-Based Privacy Preserving Camera Hannah Kirkland and S. J. Koppal arXiv 2023 — TCV CVPRW 2023 — WiCV CVPRW 2023 (extended abstract)

C33 Energy-Efficient Adaptive 3D Sensing Brevin Tilmon, Zhanghao Sun, S. J. Koppal, Yicheng Wu, Georgios Evangelidis, Ramzi Zahreddine, Guru Krishnan, Sizhuo Ma and Jian Wang CVPR 2023

**C32** Give me some room please! Personal space bubbles for safety and performance Karina LaRubbio, Ethan Wilson, **S. J. Koppal**, Sophie Jörg and Eakta Jain IEEE VR Conference 2023

 ${\bf C31}$  Optical MEMS enable next generation solutions for robot vision and human-robot interaction

Daniel Lovell, Veljko Milanovic, Abhishek Kasturi, Frank Hu, Karan Soni, Derek Ho, Bryan H. Atwood, Lj Ristic, Xiaomeng Liu, and S. J. Koppal SPIE OPTO 2022

**C30** SaccadeCam: Adaptive Visual Attention for Monocular Depth Sensing International Conference on Computer Vision (ICCV) 2021 B. Tilmon and **S. J. Koppal** 

C29 Design and Fabrication of a Forward View Scanner on SIOB with Latch Structure for Improved Vertical Orientation
IEEE MEMS 2021
D. Wang, D. Zheng, S. J. Koppal, B. Sun and H. Xie

C28 Towards a MEMS-based Adaptive LIDAR
3DV 2020
F. Pittaluga, Z. Tasneem, J. Folden, B. Tilmon, A. Chakrabarti and S. J. Koppal

C27 FoveaCam: A MEMS Mirror-Enabled Foveating Camera ICCP 2020 B. Tilmon, E. Jain, S. Ferrari, and S. J. Koppal

C26 Revealing Scenes by Inverting Structure from Motion Reconstructions
CVPR 2019 Best Paper Finalist
F. Pittaluga, S. J. Koppal, S. Kang and S. Sinha

C25 A Large Aperture 2-Axis Electrothermal MEMS Mirror for Compact 3-D LiDAR
2019 International Conference on Optical MEMS and Nanophotonics
D. Wang, C. Watkins, M. Aradhya, S. J. Koppal and H. Xie

C24 A Compact Omnidirectional Laser Scanner Based on an Electrothermal Tripod MEMS Mirror for LiDAR
Transducers 2019
D. Wang, C. Watkins, S. J. Koppal, M. Li, Y. Ding and H. Xie

C23 EyeVEIL: Degrading Iris Authentication in Eye-Tracking Headsets ETRA 2019B. John, S. J. Koppal and E. Jain

**C22** Learning Privacy Preserving Encodings through Adversarial Training IEEE Winter Conference on Applications in Vision (WACV), 2019 F. Pittaluga, **S. J. Koppal** and A. Chakrabarti

C21 Directionally Controlled Time-of-Flight Ranging for Mobile Sensing Platforms Robotics Science and Systems (RSS), 2018
Z. Tasneem, D. Wang, H. Xie and S. J. Koppal

C20 An Integrated Forward-View 2-Axis MEMS Scanner for Compact 3D LIDAR NEMS 2018 *Best Student Paper Award*D. Wang, S. Rojas, A. Shuping, Z. Tasneem, S. J. Koppal and H. Xie

C19 A Compact 3D LIDAR Based on an Electrothermal Two-Axis MEMS Scanner for Small UAV
SPIE 2018
D. Wang, S. Strassle, A. Stainsby, Y. Bai, S. J. Koppal and H. Xie

C18 Designing Light Filters to Detect Skin Using a Low-powered Sensor
SoutheastCon 2018
M. Tariq, A. Ghosh, K. Badillo-Urquiola, A. Jha, S. J. Koppal, and P. J. Wisniewski

C17 Tracking Radioactive Sources through Sensor Fusion of Omnidirectional LIDAR and Isotropic Rad-detectors
3DV 2017
K. Henderson, K. Stadnikia, A. Enqvist and S. J. Koppal

C16 A Compact MEMS-Based Wide-Angle Optical Scanner
International Conference on Optical MEMS and Nanophotonics (OMN), 2017
B. Yang, L. Zhou, X. Zhang, D. Wang, S. J. Koppal and H. Xie

C15 Situational Information Guidance for Revised Detection Limits Nuclear Science Symposium / Medical Imaging Conference 2017 K. Stadnikia, K. Henderson, S. J. Koppal and A. Enqvist

C14 A Wide-angle Immersed MEMS Mirror and Its Application in OCT International Conference on Optical MEMS and Nanophotonics, 2016 X. Zhang, L. Zhou, C. Duan, D. Zheng, S. J. Koppal, and H. Xie

C13 Data Fusion for a Vision-Radiological System: Calibration Algorithm Response to Sensor Location
INMM 2016
K. Stadnikia, A. Martin, P. Riley, K. Henderson, S. J. Koppal and A. Enqvist

C12 Focal flow: Measuring distance and velocity with defocus and differential motion
ECCV 2016 Best Student Paper
E. Alexander, Q. Guo, S.J. Koppal, S.J. Gortler, and T. Zickler

C11 Sensor-level privacy for thermal cameras
International Conference on Computational Photography (ICCP), 2016
F. Pittaluga, A. Zivkovic and S. J. Koppal

C10 Low-cost depth and radiological sensor fusion to detect moving sources 3DV, 2015
P. Riley, A. Enqvist and S. J. Koppal

C09 Privacy preserving optics for miniature vision sensorsConference on Computer Vision and Pattern Recognition (CVPR), 2015F. Pittaluga and S. J. Koppal

**C08** Data Fusion for a Vision-Radiological System for Source Tracking and Discovery Advancements in Nuclear Instrumentation Measurement Methods and their Applic., 2015 A. Enqvist and **S. J. Koppal**  C07 MEMS mirrors submerged in liquid for wide-angle scanning
International Conference on Solid-State Sensors, Actuators and Microsystems, 2015
X. Zhang, R. Zhang, S. J. Koppal, E. Butler, X. Cheng and H. Xie

C06 Wide-angle micro sensors for vision on a tight budgetConference on Computer Vision and Pattern Recognition (CVPR), 2011.S. J. Koppal, I. Gkioulekas, T. Zickler and G. Barrows

C05 Shadow cameras: Reciprocal views from illumination masksInternational Conference on Computer Vision (ICCV), 2009.S. J. Koppal and S. G. Narasimhan

C04 Temporal dithering of illumination for fast active visionEuropean Conference on Computer Vision (ECCV), 2008.S. G. Narasimhan, S. J. Koppal and S. Yamazaki

C03 Novel depth cues from uncalibrated near-field lighting International Conference on Computer Vision (ICCV), 2007.S. J. Koppal and S. G. Narasimhan

C02 Clustering appearance for scene analysisConference on Computer Vision and Pattern Recognition (CVPR), 2006.S. J. Koppal and S. G. Narasimhan

C01 Structured light from scattering media
International Conference on Computer Vision (ICCV), 2005.
S. G. Narasimhan, S. K. Nayar, B. Sun and S. J. Koppal

#### **Book chapters**

**BC02 Koppal S.J.** (2014/2019) Lambertian Reflectance. In: Ikeuchi K. (eds) Computer Vision. Springer, Boston, MA

**BC01 Koppal S.J.** (2014/2019) Diffuse Reflectance. In: Ikeuchi K. (eds) Computer Vision. Springer, Boston, MA

#### Workshops and other publications

 ${\bf W08}$  Cost-efficient Active Illumination Camera For Hyper-spectral Reconstruction arXiv, 2024

Yuxuan Zhang, T.M. Sazzad, Yangyang Song, Spencer J. Chang, Ritesh Chowdhry, Tomas Mejia, Anna Hampton, Shelby Kucharski, Stefan Gerber, Barry Tillman, Marcio F. R. Resende, William M. Hammond, Chris H. Wilson, Alina Zare, **S. J. Koppal** 

**W07** SpectralZoom: Efficient Segmentation with an Adaptive Hyperspectral Camera arXiv, 2024

Jackson Arnold, Sophia Rossi, Chloe Petrosino, Ethan Mitchell, S. J. Koppal

W06 BlockSLAM: Privacy and Security in Spatial Computing for the Gig Economy FOCUS Lab Position Paper 2022S. J. Koppal

W05 Let It Snow: Adding pixel noise to protect the user's identity 1st International Workshop on Privacy and Ethics in Eye Tracking (PrEThics), 2020 B. John, A. Liu, L. Xia, S. J. Koppal and E. Jain

W04 A low-power structured light sensor for outdoor scene reconstruction and dominant material identification
International Workshop on Projector-Camera Systems, 2012
C. Mertz, S. J. Koppal, S. Sia and S. G. Narasimhan

W03 Illustrating motion through DLP Photography PROCAMS, 2008S. J. Koppal and S. G. Narasimhan

W02 Leveraging Gaze Data for Segmentation and Effects on Comics ACM Symposium on Applied Perception Poster, 2016I. Thirunarayanan, S. J. Koppal, J. Shea and E. Jain

W01 Taylor Series of Appearance FunctionsCMU-Robotics Institute Technical report, 2006S. J. Koppal, A. Datta, S. G. Narasimhan and K. Nishino

#### PATENTS

**P08 S. J. Koppal**, Z. Tasneem, D. Wang, H, Xie and B. Tilmon Fast foveation camera and controlling algorithms US Patent US11800205B2, 2023

**P07** Huikai Xie, **S. J. Koppal**, X. Zhang, L. Zhou and C. Duan Endoscopic oct probes with immersed mems mirrors US Patent US11259685B2, 2022

**P06 S. J. Koppal** and F. Pittaluga Optical privatizing device US Patent US10440348B2, 2019

**P05 S. J. Koppal** and Vikram Appia Time-of-Flight (TOF) Assisted Structured Light Imaging US Patent US10061028B2, 2018

#### P04 S. J. Koppal

Controlling Image Focus in Real-Time Using Gestures and Depth Sensor Data US Patent US10079970B2, 2018

#### P03 S. J. Koppal

Depth sensor data with real-time processing of scene sensor data US Patent US9767545B2, 2017

**P02** T. Zickler, **S. J. Koppal**, G. L. Barrows and I. Gkioulekas Optical micro-sensor US Patent US9176263B2, 2015

**P01 S. J. Koppal**, S.B. Kang, C.L. Zitnick, M.F. Cohen, and B.K. Ressler Stereo movie editing US Patent US8330802B2, 2012

## FUNDING AWARDS (TOTAL $\sim$ \$6.5*M*, PI SHARE $\sim$ \$3.7*M*)

**F14** DURIP: Electro-Optical Sensor Prototype with Phase/Amplitude Analysis (2024-2025) Office of Naval Research (ONR) N000142412495 Total  $\sim$  \$200,000 PI share  $\sim$  \$200,000

**F13** Simultaneous imaging of multiple targets using an electrowetting prism array (2024-2026) Office of Naval Research (ONR) through CU Boulder Total ~ 300,000 co-PI share ~ 300,000

**F12** Rapid High-Resolution Target Aerial Detection and Tracking through Deep Foveated (2023-2027) Office of Naval Research (ONR) N00014-23-1-2429 Total ~ 1M PI share ~ 1M

**F11** Re-Configurable Electro-Optical Device for Accelerating Deep-Network Training and Inference on Small Autonomous Platforms (2023-2026) Office of Naval Research (ONR) N00014-23-1-2363 Total ~ \$360,000 PI share ~ \$360,000

**F10** FRR: Underwater Robot Navigation and Localization During Recovery by Optical Homing (2023-2026) National Science Foundation (NSF) 2330416 Total ~ \$599, 503 co-PI share ~ \$173,000

**F09** CAREER: Fast Foveation: Bringing Active Vision into the Camera (2020-2025) National Science Foundation (NSF) 1942444 Total  $\sim$  \$500,000 PI share  $\sim$  \$500,000

**F08** SITS: Hyperspectral Signals in the Soil (2020-2022) National Institute of Food and Agriculture FLA-AGR-006015 Total  $\sim$  \$1,200,000 co-PI share  $\sim$  \$250,000

**F07** Elements: Cyberinfrastructure Service for IoT-Based Construction Research and Applications (2020-2022) National Science Foundation (NSF) Total ~ \$455, 114.00 co-PI share ~ \$11,000 **F06** Dynamic Light Transport Acquisition and Applications to Computational Illumination (2019-2022) National Science Foundation (NSF) 1909729 Total ~ \$500,000 PI share ~ \$250,000

 $\label{eq:F05} \begin{array}{l} \mbox{F05 Directionally Controlled Time-of-Flight Sensors: Algorithms, Optical and Imaging} \\ (2018-2022) \\ \mbox{Office of Naval Research (ONR) N00014-18-1-2663} \\ \mbox{Total} \sim \$780,000 \mbox{ PI share} \sim \$390,000 \end{array}$ 

**F04** Novel Micro-LIDAR design and sensing algorithms for flapping-wing Micro-aerial Vehicle (2015-2019) National Science Foundation (NSF) 1514154 Total  $\sim$  \$400,000 PI share  $\sim$  \$200,000

**F03** Radiological Source Detection and Tracking Based on Multi-Sensor Data Fusion (2014-18) Department of Homeland Security (DHS) 2014-DN-077-ARL083-03 Total  $\sim$  \$890,000, co-PI share  $\sim$  \$460,000

**F02** Wide-angle optics for micro-LIDAR sensor (2018-2020) MIST Center Award, Total  $\sim$  \$100000, PI share  $\sim$  \$50000

F01 Texas Instruments Embedded Processing University Funding Award (2013)

## **TEACHING**

 ${\bf T03}$  Advanced Robot Perception, Spring 2021-present

I developed this course from scratch at UF. It teaches students effective wielding of a subset of deep learning approaches that are practically useful for building perception algorithms for robotic systems. The focus here is on data from real sensors in robotic and autonomous scenarios, such as thermal cameras (both MWIR and LWIR), event cameras, stereo cameras, high-speed cameras, LIDAR sensors and optical processors.

T02 Computational Photography, Fall 2014-present

Latest rating 4.3 for undergraduates and 4.5 for graduate students

I developed this Computational Photography course from scratch at UF, and which received its official course numbers recently (EEL 4403/5406). This course contains hands-on lab activity, with simple but powerful computational photography techniques.

T01 Signals and Systems, Spring 2015-present

Latest rating 3.8 for undergraduates

EEL 3135 (Signals and Systems) is a core course for an undergraduate degree in Electrical and Computer Engineering at UF. The goal of the course is to garner a practice-based understanding of time-varying information (signals) and the software/circuits needed to process these (systems). I exploit the flipped nature of the class to help students develop abstract complex number processing skills.

#### **STUDENTS**

## Ph.D. Students

**D13** Xiaoyang Zhang, graduated 2016 (co-advised) Thesis: Robust Electrothermally Actuated Scanner for Fiberoptic Endoscopic Imaging and Wide-angle Optics Apple (first appointment)

**D12** Francesco Pittaluga, graduated 2019 Thesis: Privacy Preserving Computational Cameras 2018 Microsoft Research Dissertation Awardee NEC Labs (first appointment)

**D11** Kristofer Henderson, graduated 2020 Thesis: Sensor Fusion for Non-Line-of-Sight Visualization and Imaging Lockheed Martin (first appointment)

**D10** Dingkang Wang, graduated 2021 Thesis: Quasi-static forward scanning electrothermal MEMS mirrors for LIDAR Texas Instruments (first appointment)

**D09** Xiaomeng Liu, graduated 2022 Thesis: Lightweight Light Transport for Non-line-of-sight Imaging

**D08** Brevin Tilmon, graduated 2023 Thesis: Foveated Computational Imaging Quidient (first appointment)

**D07** Justin Folden, graduated 2024 Thesis: Foveated Depth Sensing (2023)

 ${\bf D06}$ Hannah Kirkland, expected Dec 2026

 ${\bf D05}$ Yuxuan Zhang, expected Dec<br/> 2026

D04 Mehran Keivanimehr, expected Dec 2026

D03 Dexter Burns, expected Dec 2029

 ${\bf D02}$  Michael Tomadakis, expected Dec 2029

D01 Jacob Carter, expected Dec 2029

#### **Thesis committees**

Yiming Cui Electrical and Computer Engineering Dylan Stewart Electrical and Computer Engineering Taylor Harvey Nuclear Engineering Science Xiaohui Huang Computer Science Washington Garcia Computer Science Heng Qiao Electrical and Computer Engineering Guohao Yu Electrical and Computer Engineering Jiaqi Zhang Electrical and Computer Engineering Keerthiraj Nagaraj Electrical and Computer Engineering Rajendra Bhat Electrical and Computer Engineering Richard Al-Bayaty Electrical and Computer Engineering Manu Chandran Electrical and Computer Engineering Pratik Brahma Electrical and Computer Engineering Chiranjib Sur Computer Engineering Kelsey Stadniki Nuclear Engineering Sciences Xiaohui Huang Computer Science Inchul Choi Computer Science Xianjin Dai Biomedical Engineering Paul Johns Nuclear Engineering Science

## **SERVICE**

 ${\bf S05}$  PAMI Chair for International Conference on Computational Photography (ICCP) 2023

S04 Area chair for Computer Vision and Pattern Recognition (CVPR) 2019/2020/2023/2024

 ${\bf S03}$  Co-chair for Cameras and Computational Displays (CCD) 2018 workshop held in conjunction with CVPR 2018/2019

 ${\bf S02}$  Posters/Demos co-chair for International Conference on Computational Photography (ICCP) 2018 and 2020

S01 Reviewer for Scholarly Journals/Conferences

IEEE Pattern Analysis and Machine Intelligence (PAMI), IEEE Transactions on Image Processing (TIP), International Journal on Computer Vision (IJCV), Computer Vision and Pattern Recognition (CVPR), European Conference on Computer Vision (ECCV), International Conference on Computer Vision (ICCV), International Conference on Computational Photography (ICCP)

## **INVITED TALKS AND SEMINARS**

**IT 34** Adaptive Attention: Bringing Active Vision into the Camera University of Southern California Los Angeles, CA (October 2023)

**IT 33** Adaptive Attention: Bringing Active Vision into the Camera University of Colorado, Boulder Boulder, CO (February 2023)

**IT 32** Adaptive Attention: Bringing Active Vision into the Camera University of Toronto Toronto, Canada (October 2022)

**IT 31** Adaptive Attention: Bringing Active Vision into the Camera University of Washington Seattle, WA (April 2022)

**IT 30** Adaptive Attention: Bringing Active Vision into the Camera Purdue University West Lafayette, IN (February 2022)

**IT 29** Adaptive Attention: Bringing Active Vision into the Camera University of Arizona Tucson, AZ (February 2022)

**IT 28** Adaptive Attention: Bringing Active Vision into the Camera Kyoto University Kyoto, Japan (December 2021)

**IT 27** Adaptive Attention: Bringing Active Vision into the Camera Stevens Institute of Technology Hoboken, NJ (November 2021)

**IT 26** Adaptive Attention: Bringing Active Vision into the Camera Cornell University Ithaca, NY (November 2021)

**IT 25** Adaptive Attention: Bringing Active Vision into the Camera Simon Fraser University Vancouver, Canada (September 2021)

**IT 24** Adaptive Attention: Bringing Active Vision into the Camera Oregon State University Corvallis, OR (September 2021)

**IT 23** Adaptive Attention: Bringing Active Vision into the Camera Toyota Technical Institute Chicago Chicago, IL (August 2021)

**IT 22** Fast Foveating Sensors University of Buffalo Buffalo, NY (April 2021)

**IT 21** Fast Foreating Cameras Optical Society of America (OSA) Imaging Systems and Applications Vancouver, Canada (June 2020)

**IT 20** Fast Foveating Cameras Carnegie Mellon University Vision and Autonomous Systems (VASC) Seminar Pittsburgh, PA (Feb 2020)

**IT 19** Fast Foreating Cameras Computer Vision and Pattern Recognition (CVPR) Area Chair Workshop La Jolla, CA (Feb 2020) **IT 18** Fast Foreating Cameras Rice University Houston, TX (Feb 2020)

**IT 17** Fast Foreating Cameras Rutgers University New Brunswick, NJ (Oct 2019)

**IT 16** Selective Imaging with Computational Cameras Snap Research Lab New York, NY (Oct 2019)

**IT 15** Fast Foreating Cameras Texas Photonics Center and Center for Digital MEMS University of Texas Dallas, TX (April 2019)

**IT 14** Fast Foveating Cameras CVPR AC Workshop La Jolla, CA, (Feb 2019)

**IT 13** Fast Foveating Cameras Institute for Virtual Environments and Video Games, University of California Irvine, CA (Feb 2019)

**IT 12** Fast Foreating Cameras Banff International Research Station for Mathematical Innovation and Discovery (BIRS), Computational Light Transport Workshop Banff, Canada, (Feb 2019)

**IT 11** Optics and Sensing for Small Vision Platforms FAU I-SENSE Boca Raton, FL (Jan 2019)

**IT 10** Toward Miniature Computer Vision Sensors OSA Imaging Systems and Applications Orlando, FL (June 2018)

**IT 09** Small Vision Sensors for Phenomics Phenome Tucson, AZ (February 2018)

**IT 08** Towards Privacy Preserving Cameras ASU SENSIP Phoenix, AZ (2018)

**IT 07** Wide-FOV Sensing & Optical Processing for Small Vision Applications OSA Incubator on Small Eyes and Smart Minds Washington, DC (October 2017)

IT 06 Towards Privacy Preserving Cameras

IRISA-Rennes Rennes, France (2017)

**IT 05** Towards Privacy Preserving Cameras Technicolor R&D Labs Rennes, France (2017)

**IT 04** Towards Privacy Preserving Cameras INRIA-Bordeaux/LPN2 Bordeaux, France (2017)

**IT 03** Towards Privacy Preserving Cameras UCF CRCV Orlando, FL (2017)

**IT 02** Towards Micro Vision Sensors UCF CREOL Orlando, FL (2017)

**IT 01** Privacy Preserving Sensors University of Miami CSD Miami, FL (2015)

#### **MEDIA COVERAGE**

 $\mathbf{MC}$ 07 "Fresh Coffee from Florida? Scientists are Brewing up the Possibility" freshproduce.com 2021

 $\mathbf{MC}$ 06 "Revealing Scenes by Inverting SFM Reconstructions" Computer Vision News 2020

MC 05 "Best of ECCV: Focal Flow" Computer Vision News 2016

 $\mathbf{MC}$ 04 "RoboBees Can Fly and Swim. What's Next? Laser Vision" Smithsonian Magazine 2015

MC 03 "RoboBee Lidar Useful for Robocars?" IEEE Spectrum 2015

 $\mathbf{MC}$   $\mathbf{02}$  "'RoboBees' with Laser Eyes Could Locate Disaster Victims" NBC News 2015

 $\mathbf{MC}$  01 "Scientists Are Using Lasers to Teach RoboBees to See" Smithsonian Magazine 2015

# OTHER INFORMATION

Languages: English, Hindi, Kannada Citizenship: U.S.A Lab Website: focus.ece.ufl.edu