

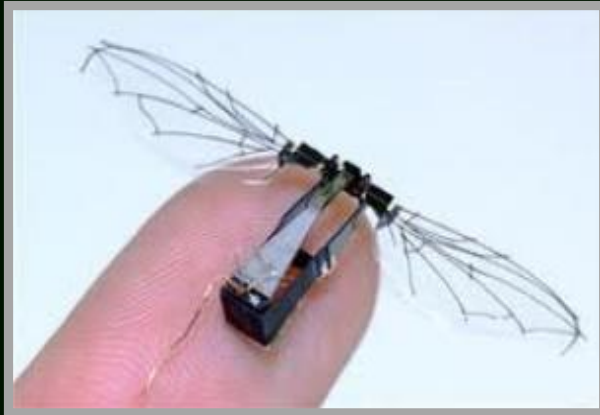
Privacy Preserving Optics for Miniature Vision Sensors

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Electrical and Computer Engineering

The next wave of small devices



Microrobots



Medical devices



Remote sensor nodes

In the future, there will be trillions of networked miniature cameras.

Privacy in the Face of Trillions of Eyes



Security and Defense



Wearable Technology



Journalism and Media



Health and Medicine

Some groups are particularly vulnerable

Our ideas

1) Pre-Capture Privacy

- Privacy *before* capture

2) Miniaturizing Algorithms

- High performance
- Smallest mass and volume

We show mobile scale prototypes

Motivating Example



Group of People

We want to:

- 1) Track/Photograph everyone
- 2) Prevent face recognition

Quantitative: accurate people tracking and
low recognition rate

Block Diagram



Group of People



1. Tracking people with privacy



Modulating Optics



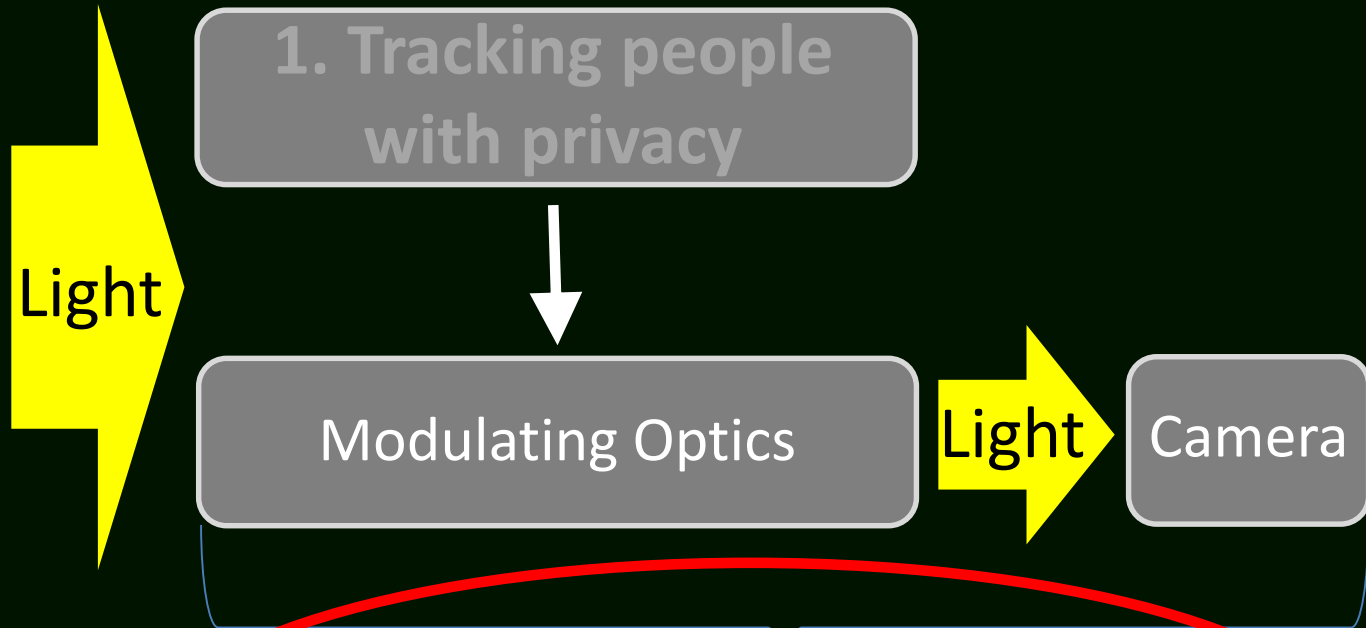
Camera

2. Photographing people with privacy

Block Diagram



Group of People

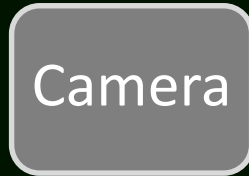
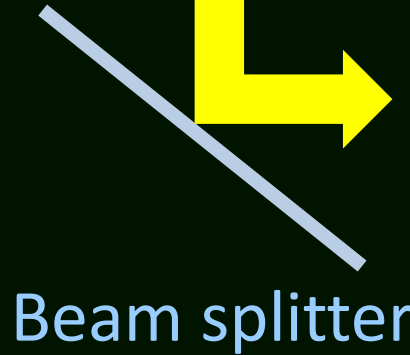
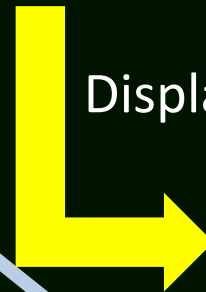


2. Photographing people with privacy

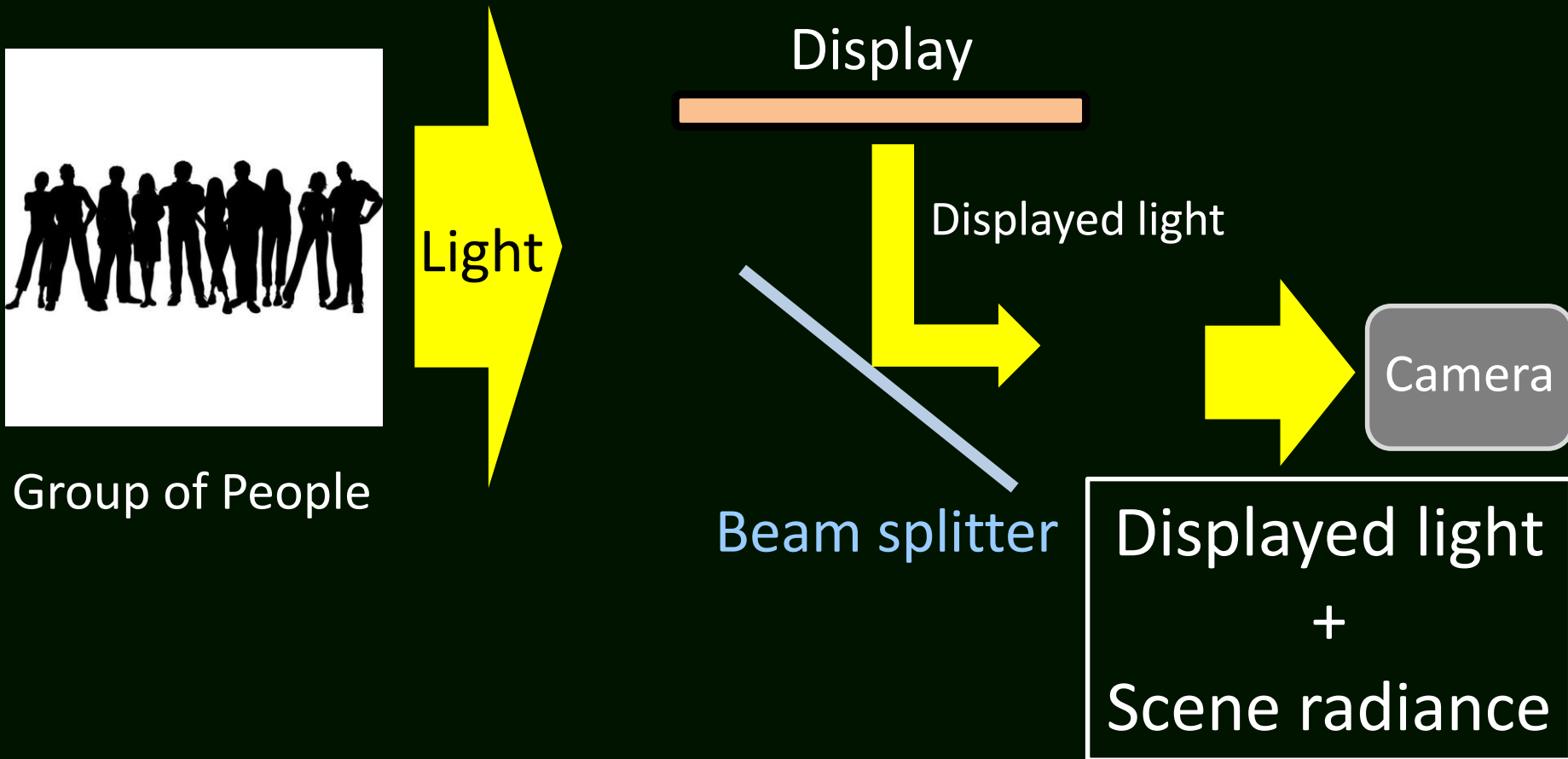
Ray Diagram



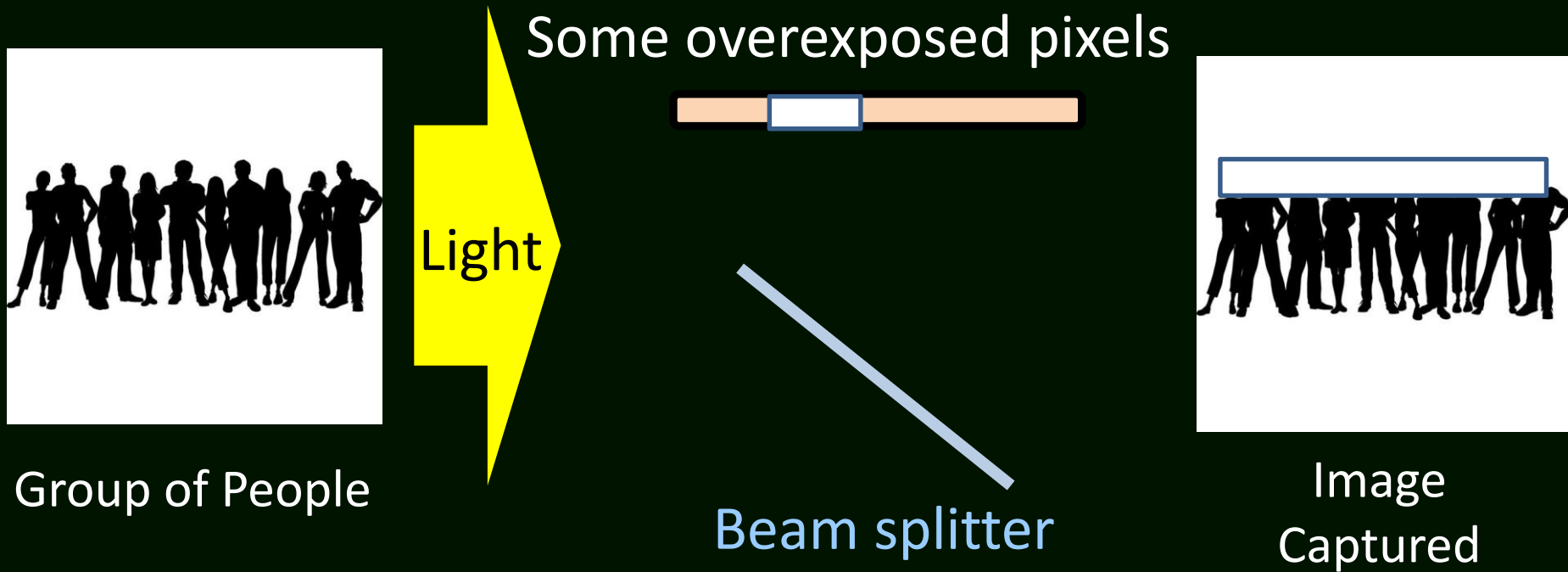
Group of People



Ray Diagram



Pre-Capture White-Out



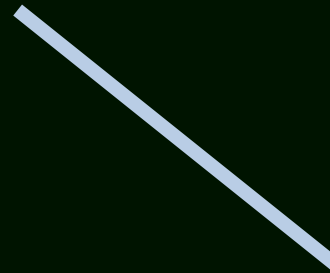
Optical K-Anonymity



Group of People



Optically superimpose face



Beam splitter

Optical K-anonymity

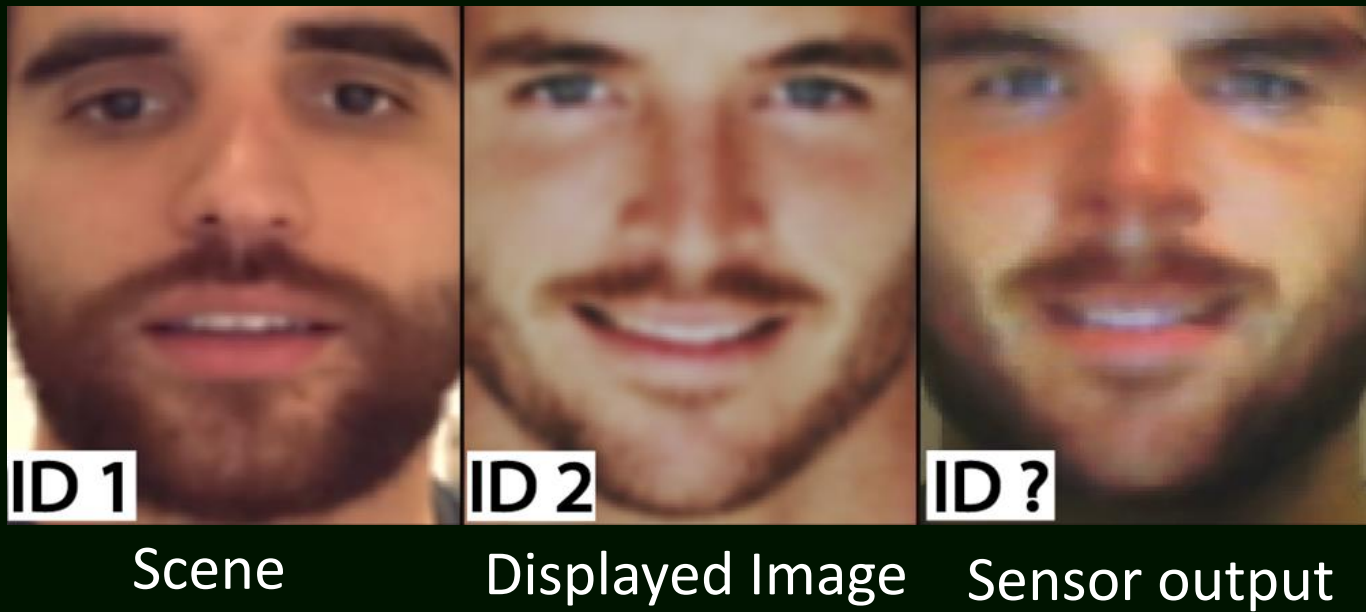


Image Formation Model

Image pixel

Scene point
radiance

Pixel-radiance
map

Weight

Camera-display
transform

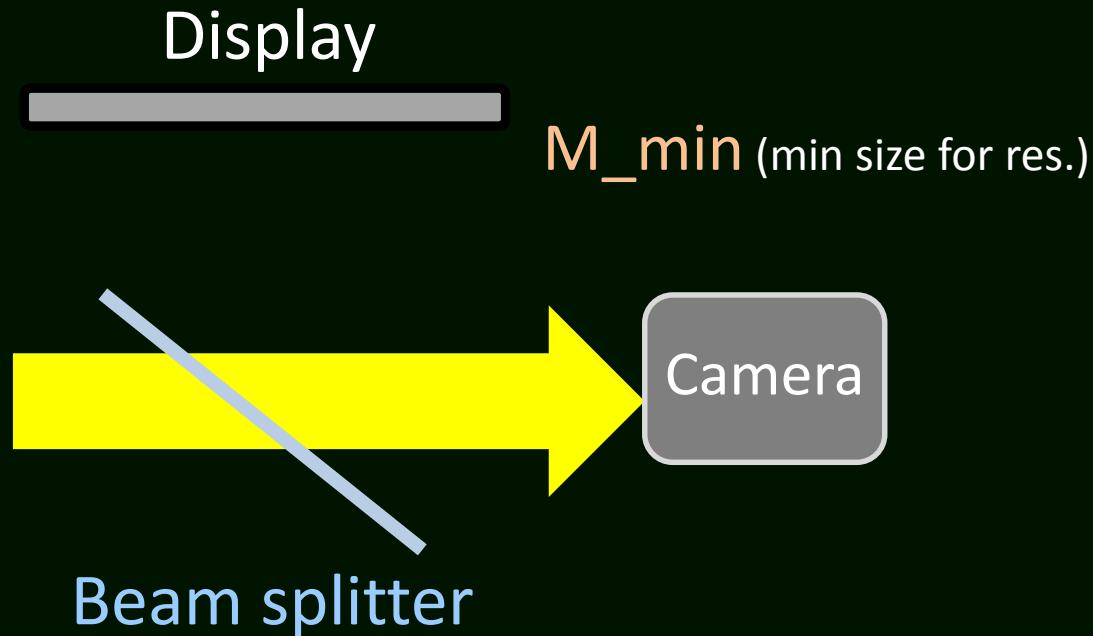
$$I(x, y) = e_p I_p + e_m \sum_{1 \leq i \leq k-1} I_{mask}(w_i F_i(H(x, y)))$$

Optical path split ratio

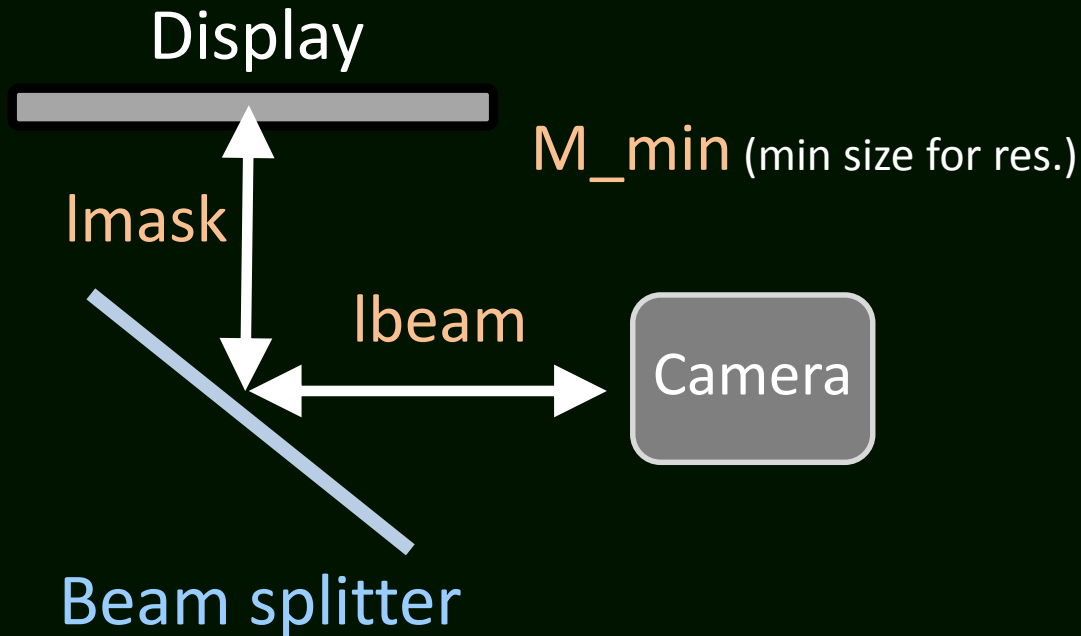
Weight sum of k-1 images

Miniaturization (Orthographic)

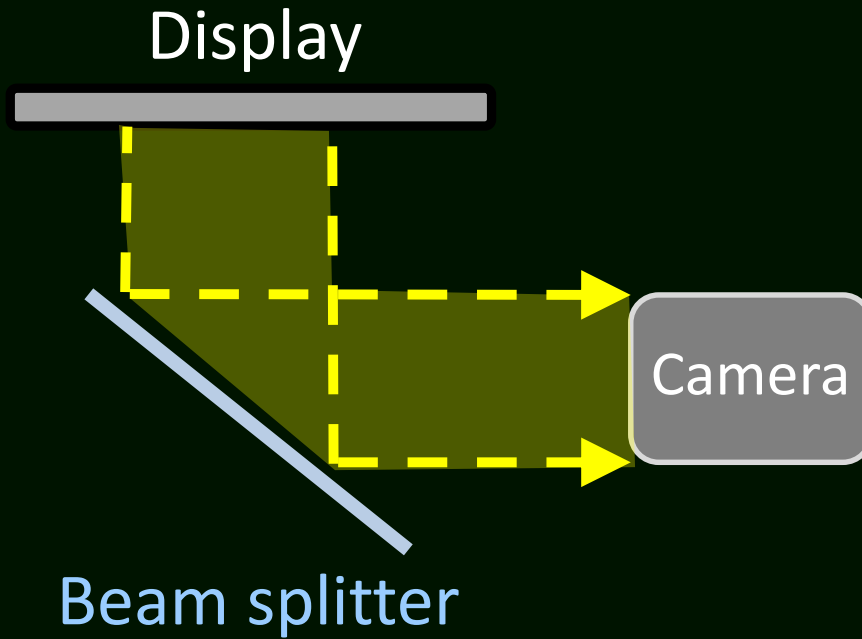
Miniaturization (Orthographic)



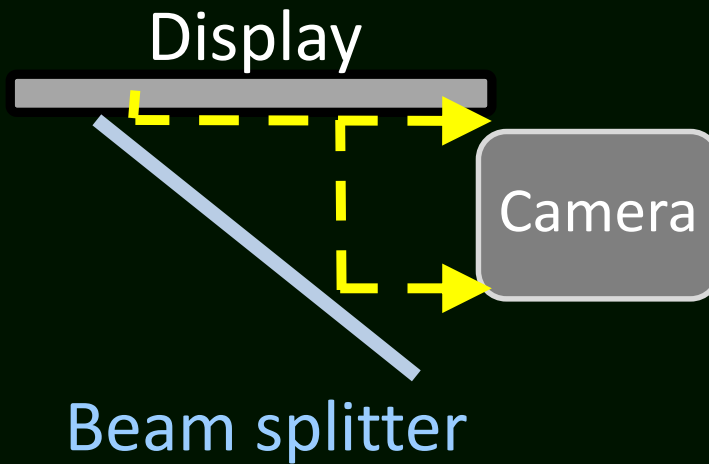
Miniaturization (Orthographic)



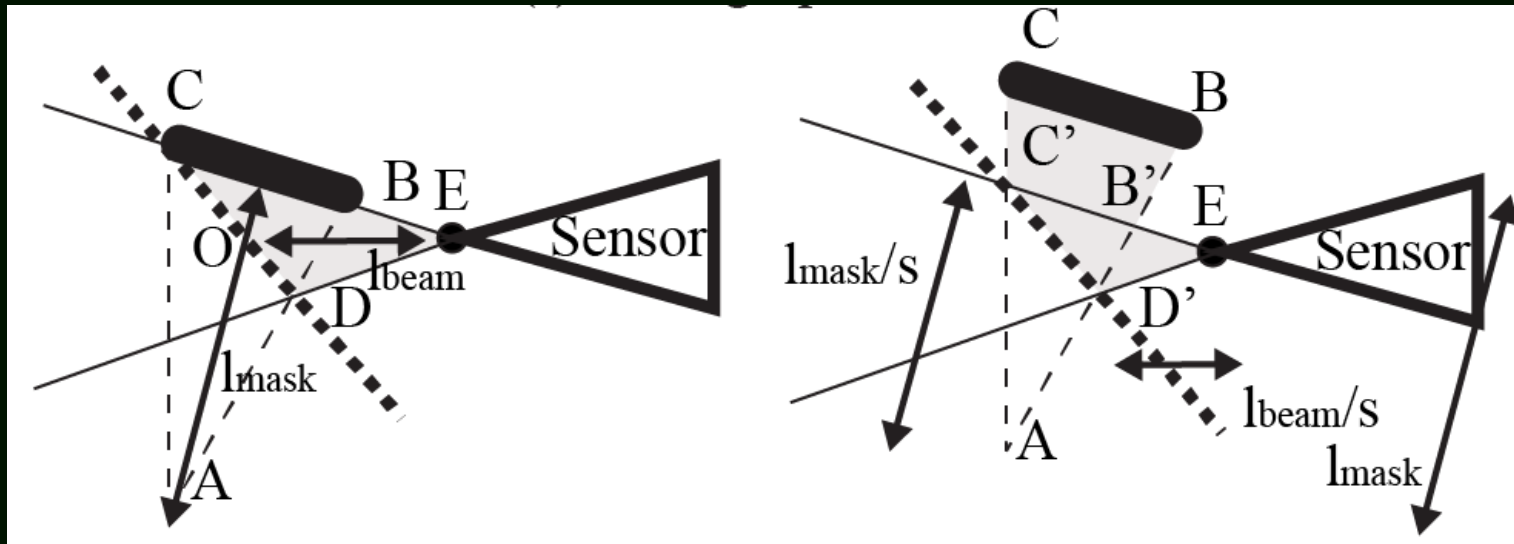
Volume occupied



Miniaturization by translation



Miniaturization (Perspective)



$$C_1 = \frac{\sin \frac{\theta}{2} \sin \phi}{2 \sin(\frac{\theta}{2} - \phi)} + \frac{\sin \frac{\theta}{2} \sin \phi}{2 \sin(\frac{\theta}{2} + \phi)}$$

$$s = \frac{M_{min} l_{mask}}{2C_1 l_{beam}^2 - M_{min} l_{mask}}$$

Please see details in the paper

Block Diagram



Group of People



1. Tracking people with privacy



Modulating Optics



Camera

2. Photographing people with privacy

Block Diagram



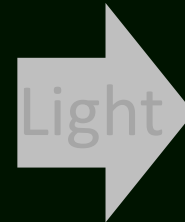
Group of People



1. Tracking people with privacy



Modulating Optics



Camera

2. Photographing people with privacy

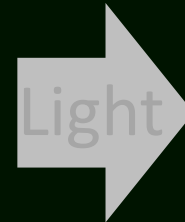
Our key ideas

- Defocus in time-of-flight (TOF) and thermal domains preserve utility and provide privacy
- Multiple defocus apertures allow privacy and utility even in visible domains

Privacy Vision Sensor 1 of 3



Group of People



2. Photographing people with privacy

Defocused time-of-flight camera



Conventional usage



With Defocus

Defocused time-of-flight camera



Conventional usage



With Defocus

Privacy Vision Sensor 2 of 3



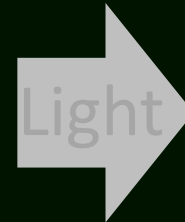
Group of People



1. Tracking people with privacy



Modulating Optics



Camera

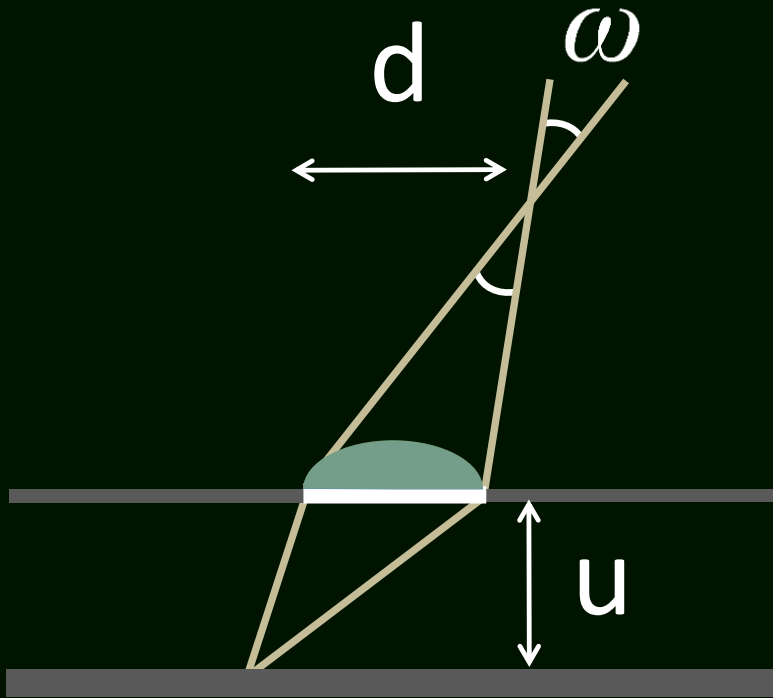
2. Photographing people with privacy

Defocused thermal camera

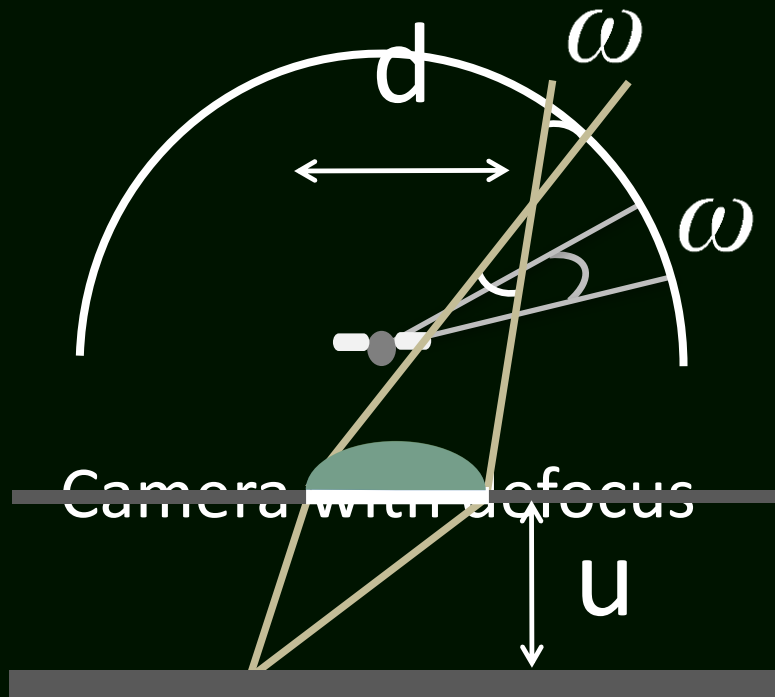


FLIR One with defocus lens

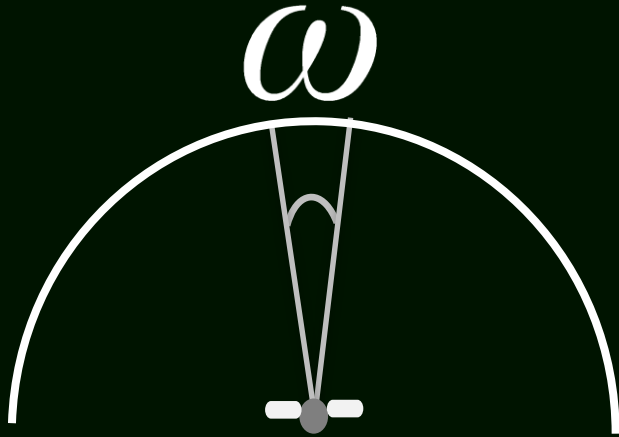
Miniaturization of defocus



Miniaturization of defocus

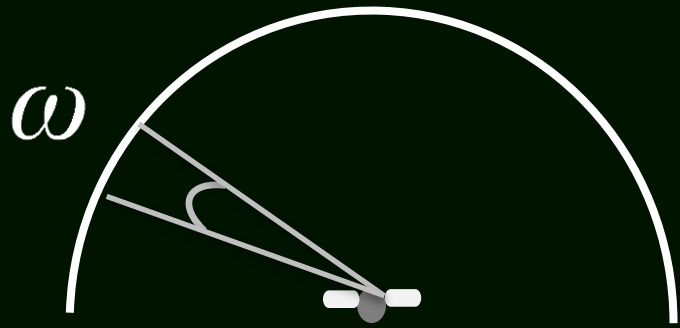


Miniaturization of defocus

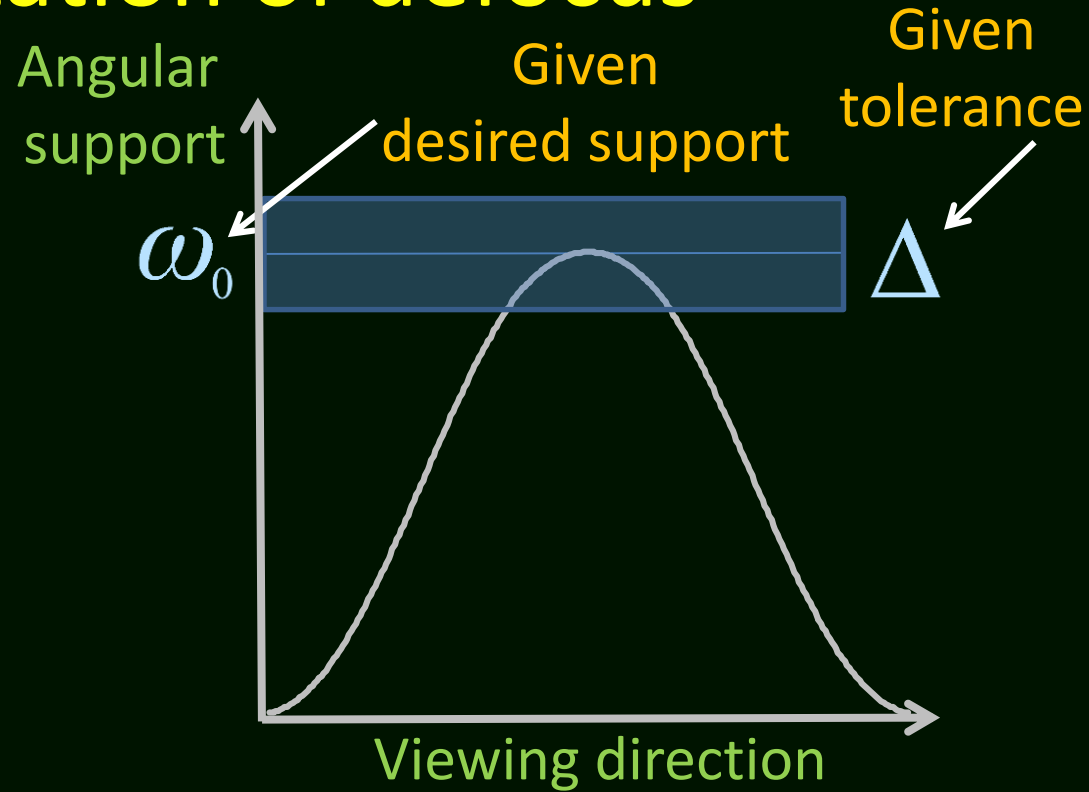


Camera with defocus

Miniaturization of defocus



Camera with defocus



Miniaturization of defocus

$\omega_0 \Delta$

Given

Our
PAMI 2013

u, d

Output

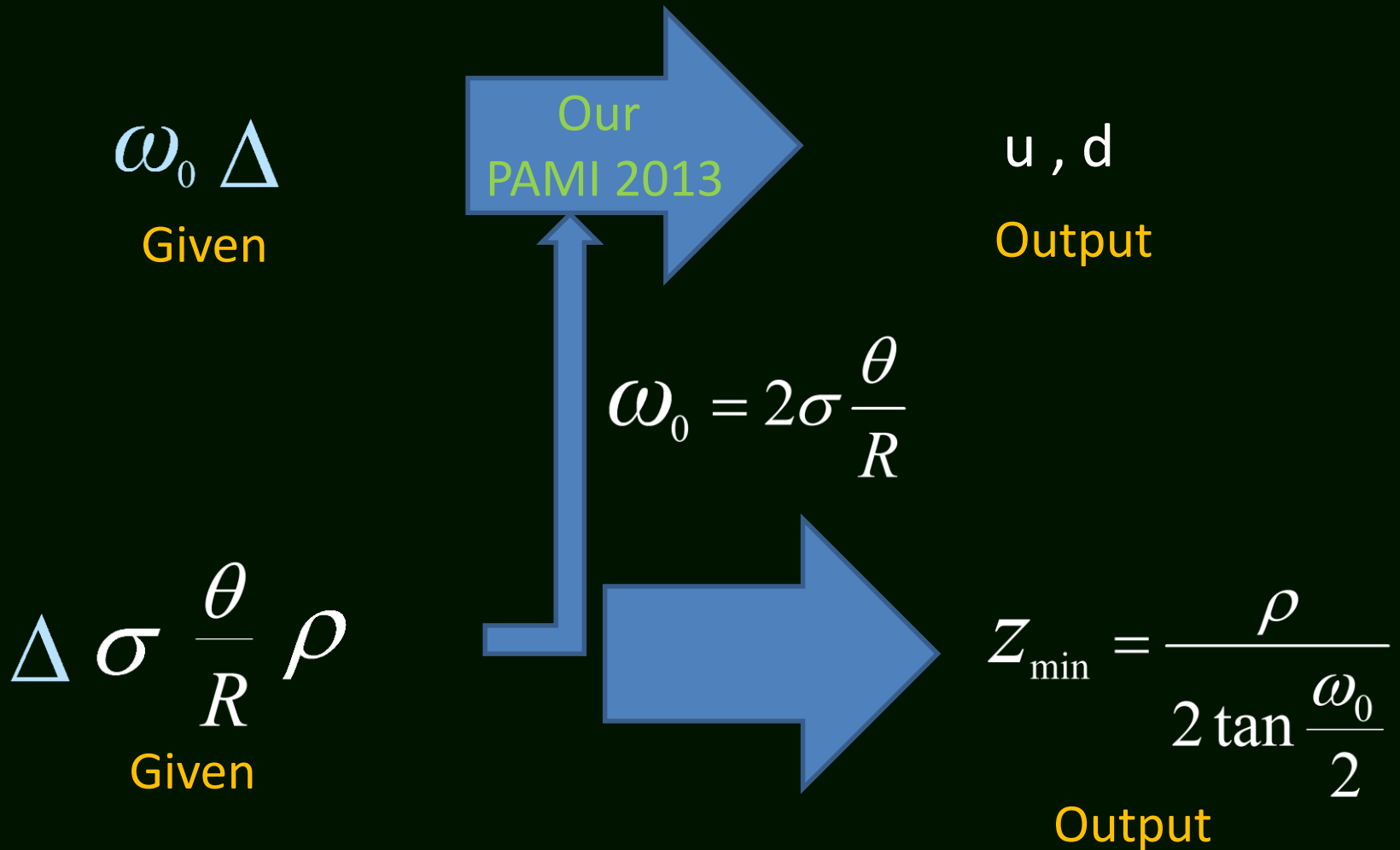
Defocus parameter
and angular res.

Biggest feature
to anonymize

$\Delta \sigma \frac{\theta}{R} \rho$

Given

Miniaturization of defocus



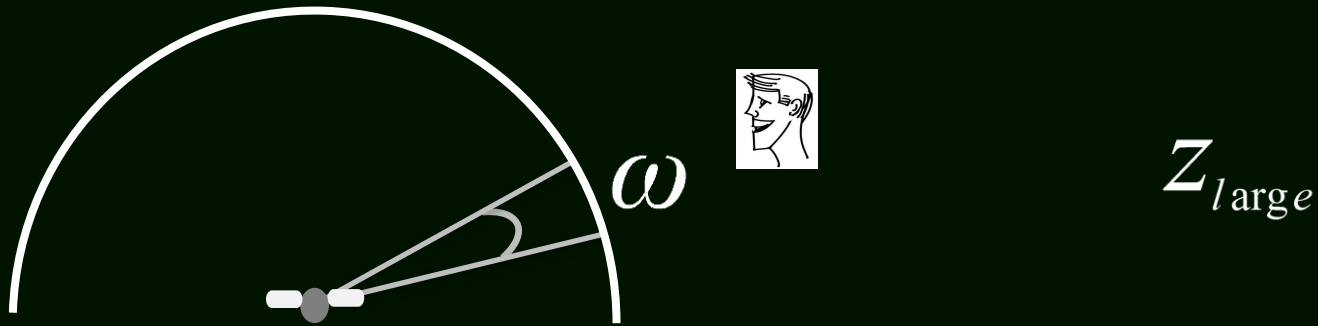
Miniaturization of defocus



Camera with defocus

$$Z_{\min} = \frac{\rho}{2 \tan \frac{\omega_0}{2}}$$

Miniaturization of defocus



Camera with defocus

Privacy Vision Sensor 3 of 3



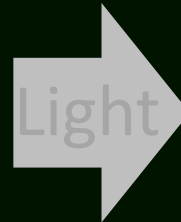
Group of People



1. Tracking people with privacy



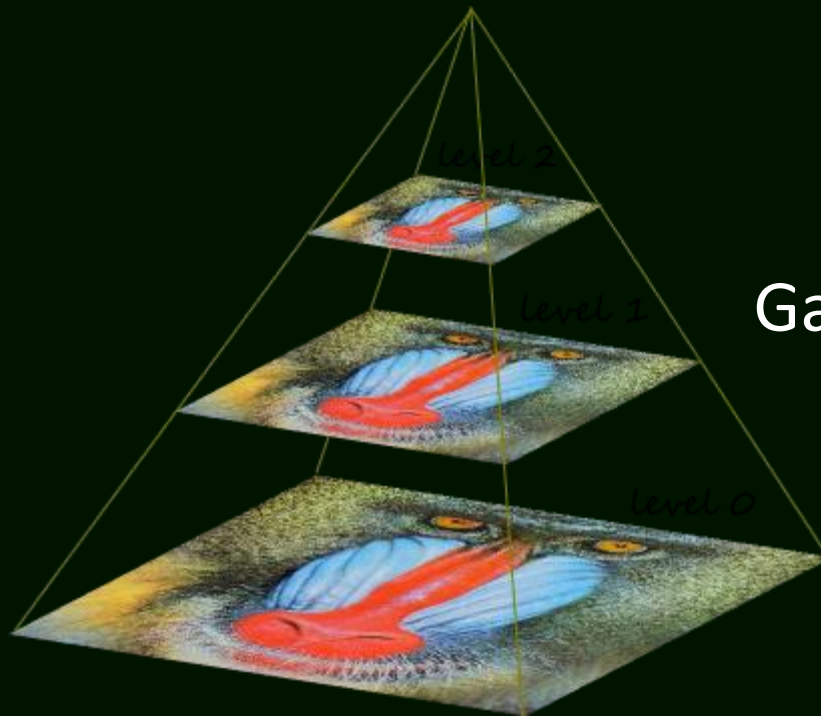
Modulating Optics



Camera

2. Photographing people with privacy

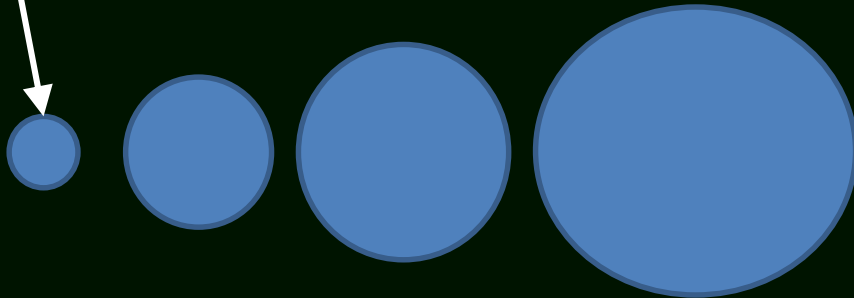
Scale space analysis



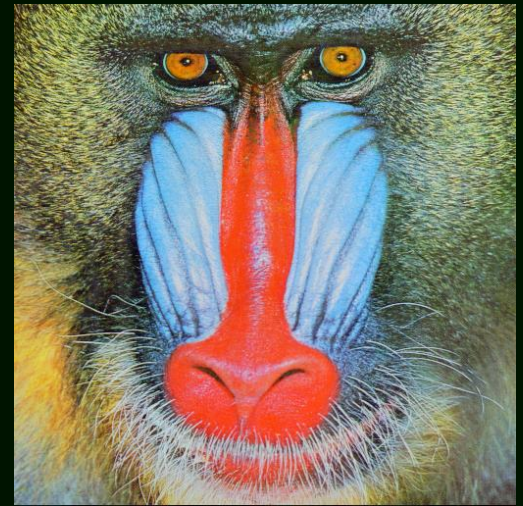
Gaussian pyramid

Scale space analysis with optical defocus

Worry about privacy here!

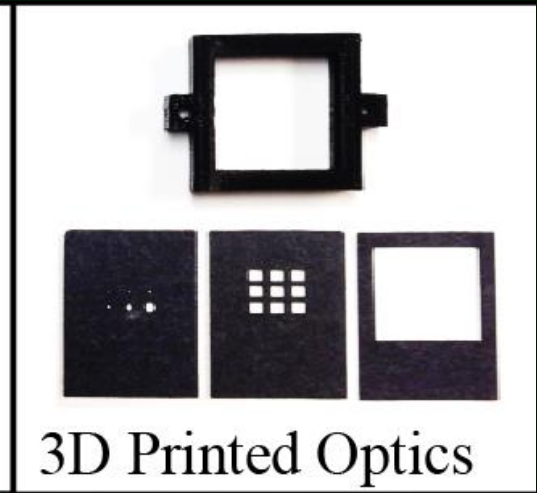


Optical apertures

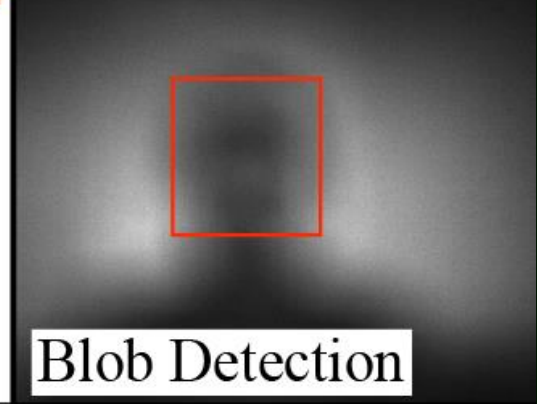


Scene

Scale space detection with optical defocus



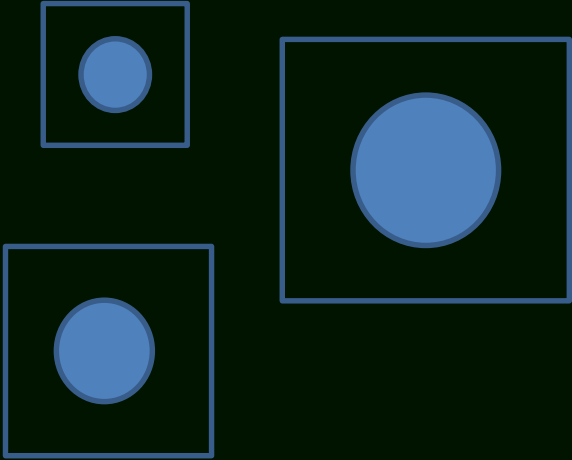
Optical Processing (Off-Board)



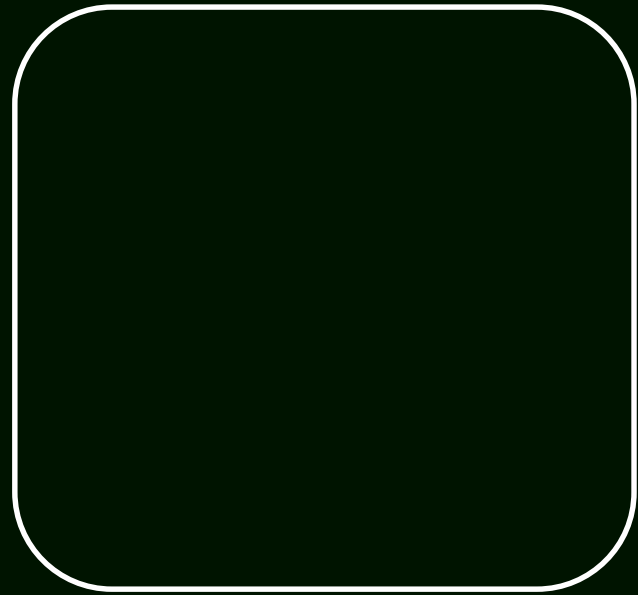
A classifier is trained on the blobs

Optical Array Miniaturization

Optical Array Miniaturization

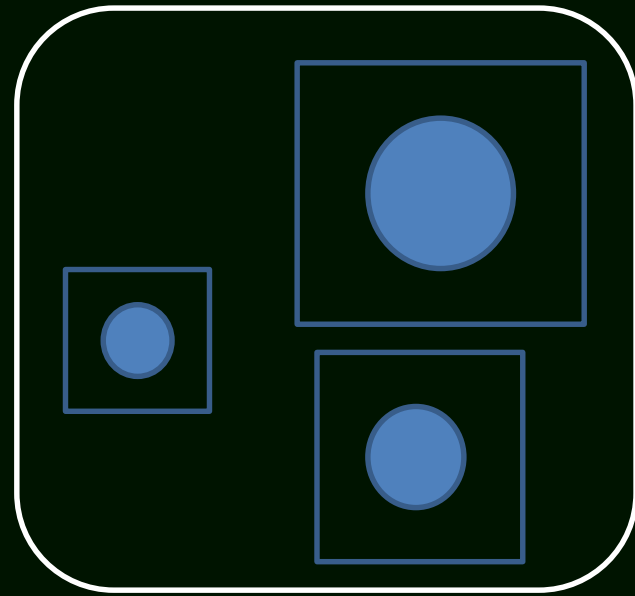


Optical elements with
mass/volume/FOV



Physical device has size limits

Optical Array Miniaturization



Optical elements with
mass/volume/FOV

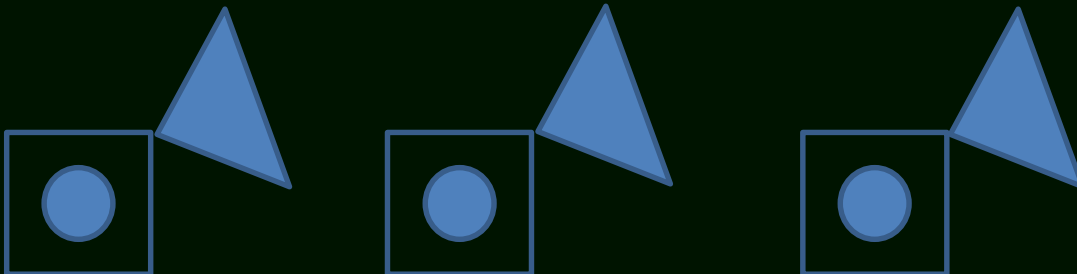
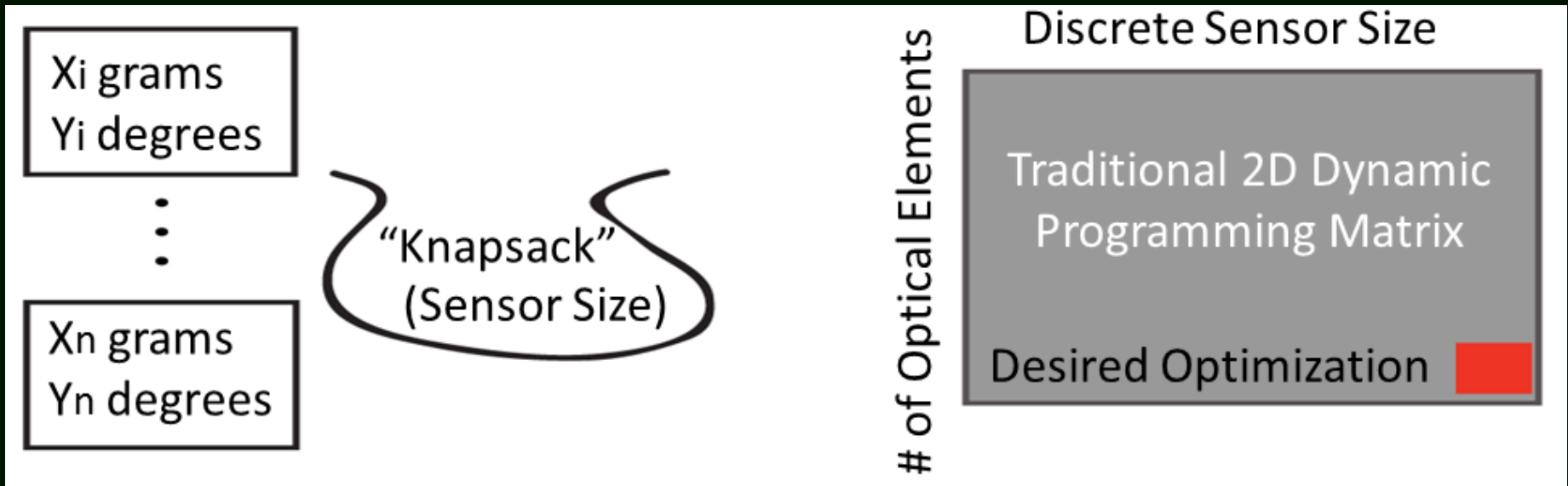
Physical device has size limits

Optical Array Miniaturization

- Has two parts
 - Selection
 - Packing

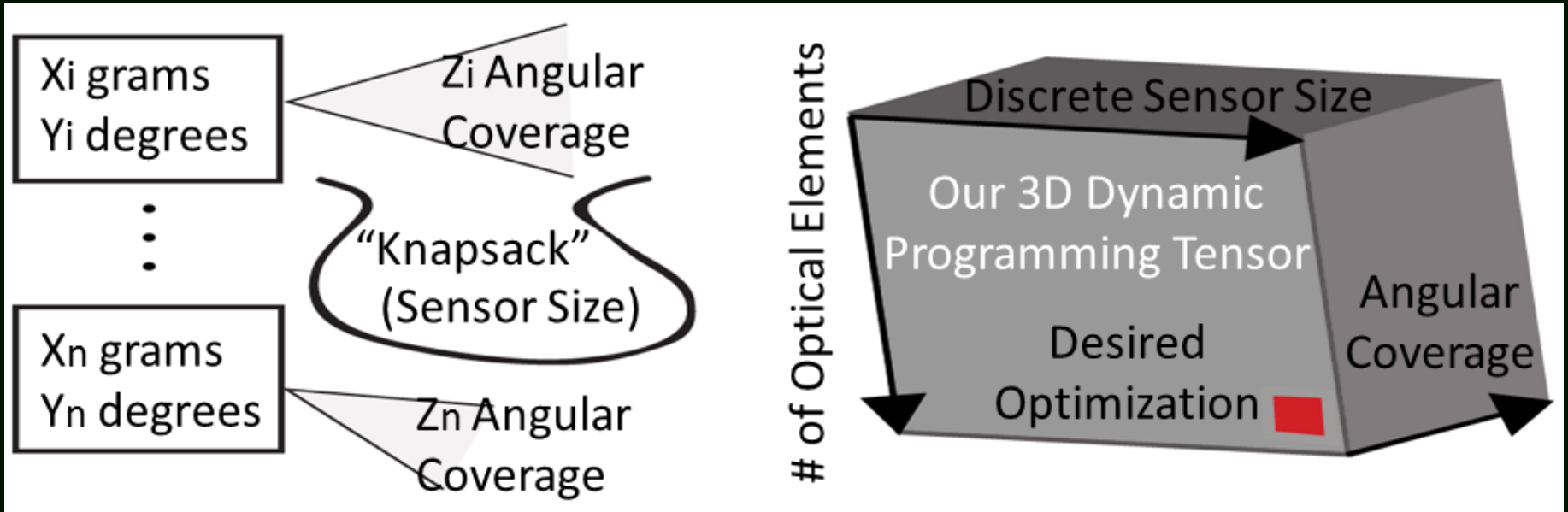
We focus on selection

Knapsack Problem



These could get added into the design

Optical Knapsack Problem



Optical Knapsack Problem

Angular
discretization

$$M[i, a, b] = 0, \text{ if } 0 \leq a \leq A, 0 \leq i \leq n \text{ and } 0 \leq b \leq \beta$$

and is recursively updated as

If $a < 0$

$$M[i, a, 0] = -\infty$$

For any other a , **for any** i

If

$$M[i - 1, a, 0] <$$

$$f_i + M[i - 1, a - a_i, 0]$$

and

$$\sum_{1 \leq b \leq \beta} M[i - 1, a, b] <$$

$$\sum_{1 \leq b \leq \beta} M[i - 1, a - a_i, b] \vee K[i, b]$$

Otherwise $\forall b$

$$\left\{ \begin{array}{l} M[i, a, 0] = \\ f_i + M[i - 1, a - a_i, 0] \\ \\ M[i, a, b] = \\ M[i - 1, a - a_i, b] \vee \\ K[i, b], b \in (1, \beta) \\ \\ M[i, a, b] = M[i - 1, a, b] \end{array} \right.$$

No magic: Pseudo-polynomial approximation

Summary



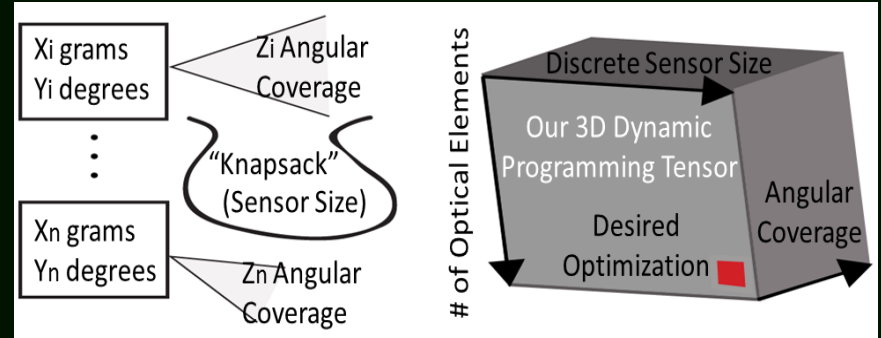
K-anonymity Camera



Defocus in thermal and TOF preserves privacy

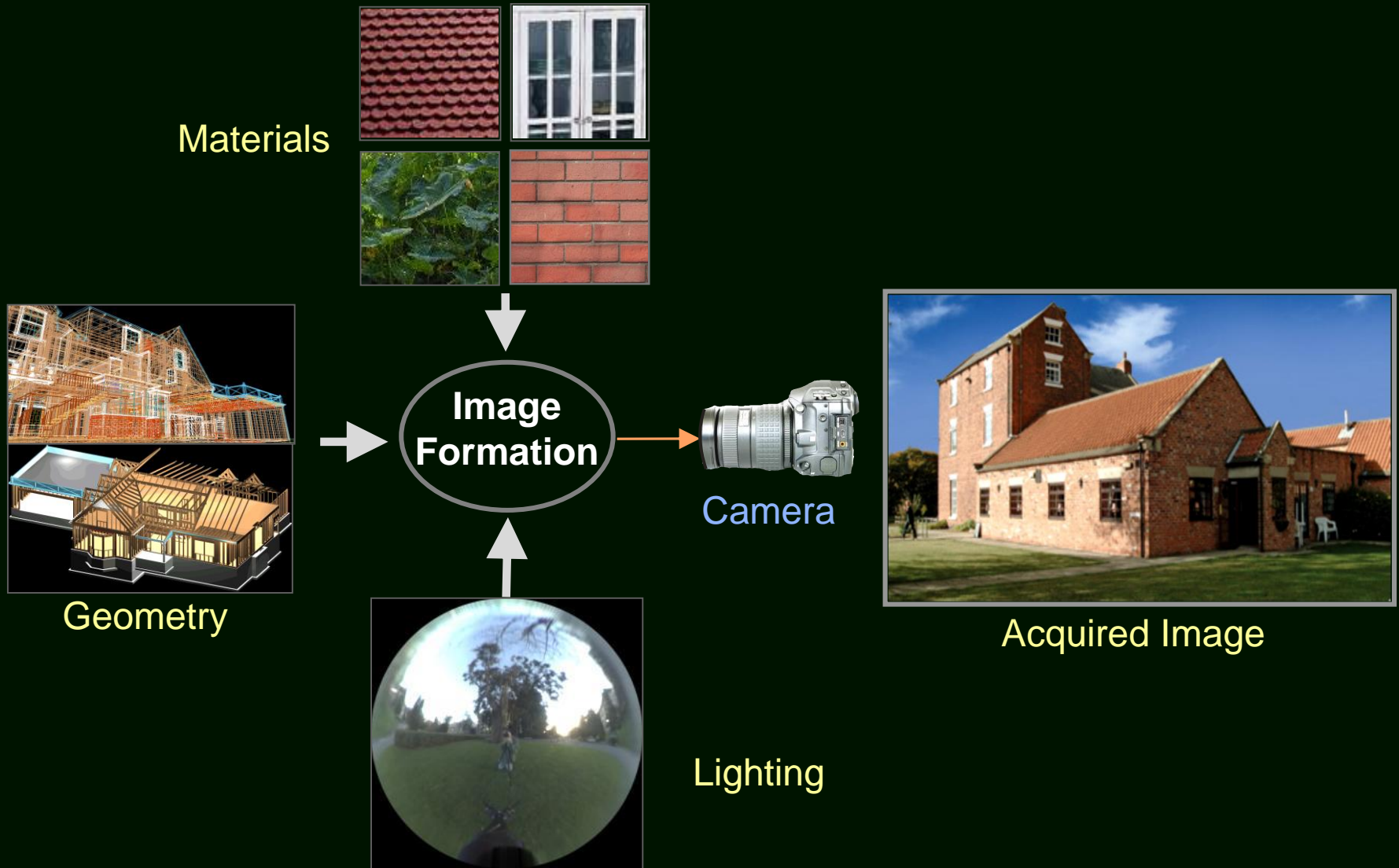


Optical scale space analysis



Optical knapsack solution

Future Work: Privacy in Image Formation



Demo at CVPR 2015



Sensor Setup



Pre-Capture White-Out