Sanjeev J. Koppal

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EXPERIENCE AND EDUCATION

Assistant Professor 2014-present University of Florida, Electrical and Computer Engineering Director of the Florida Optics and Computational Sensor (FOCUS) Lab Member of Technical Staff 2012-2014 Texas Instruments Imaging R&D Group Post-doctoral Research Associate 2009-2012 Harvard University Mentor: Prof. Todd Zickler Graduate Research Assistant 2003-2009 Robotics Institute, Carnegie Mellon University Ph.D. Robotics Aug 2009 Advisor: Prof. Srinivasa Narasimhan Undergraduate Research Assistant 1999-2003 University of Southern California B.S. Computer Science May 2003

JOURNALS

Advisor: Prof. Gaurav Sukhatme

J12 Data Fusion for a Vision-Aided Radiological Detection System: Calibration Algorithm Performance

Nuclear Instruments and Methods in Physics A, 2018

K. Stadnikia, K. Henderson, A. Martin, P. Riley, S. J. Koppal and Andreas Enqvist

J11 Focal Flow: Velocity and Depth from Differential Defocus through Motion International Journal on Computer Vision (IJCV), 2017

E. Alexander, Q. Guo, S. J. Koppal, S.J. Gortler, and T. Zickler

J10 Leveraging gaze data for segmentation and effects on comics
Transactions on Multimedia Computing (TOMM), 2017
I. Thirunarayanan, K. Khetarpal, S. J. Koppal, O. LeMeur, J. Shea and E. Jain

J09 Pre–capture privacy for small vision sensors Transactions on Pattern Analysis and Machine Intelligence (PAMI) 2016 F. Pittaluga and S. J. Koppal

J08 A survey on computational photography in the small IEEE Signal Processing Magazine, 2016

S. J. Koppal

J07 Wide-angle structured light with a scanning MEMS mirror in liquid Optics Express, 2016

X. Zhang, S. J. Koppal, R. Zhang, L. Zhou, E. Butler and H. Xie

J06 Beyond perspective dual photography with illumination masks Transactions on Image Processing (TIP), 2015

S. J. Koppal and S. G. Narasimhan

J05 Generalized assorted camera arrays: robust cross-channel registration and applic. Transactions on Image Processing (TIP), 2015

J. Holloway and K. Mitra and S. J. Koppal and A. Veeraraghavan

J04 Towards wide-angle micro vision sensors

Transactions on Pattern Analysis and Machine Intelligence (PAMI), 2013

S. J. Koppal, I. Gkioulekas, T. Young, H. Park, K. Crozier, G. Barrows and T. Zickler

J03 Exploiting DLP illumination dithering for reconstruction and photography of high-speed scenes

International Journal on Computer Vision (IJCV), 2011.

S. J. Koppal, S. Yamazaki and S. G. Narasimhan

J02 A viewer-centric editor for stereoscopic cinema

IEEE Computer Graphics and Applications (CG&A), 2011.

S. J. Koppal, L. Zitnick, M. Cohen, S. Kang, B. Ressler and A. Colburn

J01 Appearance derivatives for iso-normal clustering of scenes

Transactions on Pattern Analysis and Machine Intelligence (PAMI), 2008.

S. J. Koppal and S. G. Narasimhan

CONFERENCES

C22 Learning Privacy Preserving Encodings through Adversarial Training IEEE Winter Conference on Applications in Vision (WACV), 2019 F. Pittaluga, S. J. Koppal and A. Chakrabarti

C21 Directionally Controlled Time-of-Flight Ranging for Mobile Sensing Platforms Robotics Science and Systems (RSS), 2018

Z. Tasneem, D. Wang, H. Xie and S. J. Koppal

C20 An Integrated Forward-View 2-Axis MEMS Scanner for Compact 3D LIDAR NEMS 2018, Winner of Best Student Paper Award

D. Wang, S. Rojas, A. Shuping, Z. Tasneem, S. J. Koppal and H. Xie

C19 A Compact 3D LIDAR Based on an Electrothermal Two-Axis MEMS Scanner for Small UAV

SPIE 2018

D. Wang, S. Strassle, A. Stainsby, Y. Bai, S. J. Koppal and H. Xie

C18 Designing Light Filters to Detect Skin Using a Low-powered Sensor SoutheastCon 2018

M. Tariq, A. Ghosh, K. Badillo-Urquiola, A. Jha, S. J. Koppal, and P. J. Wisniewski

C17 Tracking Radioactive Sources through Sensor Fusion of Omnidirectional LIDAR and Isotropic Rad-detectors

3DV 2017

K. Henderson, K. Stadnikia, A. Enqvist and S. J. Koppal

C16 A Compact MEMS-Based Wide-Angle Optical Scanner International Conference on Optical MEMS and Nanophotonics (OMN), 2017 B. Yang, L. Zhou, X. Zhang, D. Wang, S. J. Koppal and H. Xie

C15 Situational Information Guidance for Revised Detection Limits Nuclear Science Symposium / Medical Imaging Conference 2017 K. Stadnikia, K. Henderson, S. J. Koppal and A. Enqvist

C14 A Wide-angle Immersed MEMS Mirror and Its Application in OCT International Conference on Optical MEMS and Nanophotonics, 2016 X. Zhang, L. Zhou, C. Duan, D. Zheng, S. J. Koppal, and H. Xie

C13 Data Fusion for a Vision-Radiological System: Calibration Algorithm Response to Sensor Location

INMM 2016

K. Stadnikia, A. Martin, P. Riley, K. Henderson, S. J. Koppal and A. Enqvist

C12 Focal flow: Measuring distance and velocity with defocus and differential motion Winner of Best Student Paper Award

European Conference on Computer Vision (ECCV), 2016

E. Alexander, Q. Guo, S.J. Koppal, S.J. Gortler, and T. Zickler

C11 Sensor-level privacy for thermal cameras

International Conference on Computational Photography (ICCP), 2016

F. Pittaluga, A. Zivkovic and S. J. Koppal

 ${f C10}$ Low-cost depth and radiological sensor fusion to detect moving sources 3DV, 2015

P. Riley, A. Enqvist and S. J. Koppal

C09 Privacy preserving optics for miniature vision sensors Conference on Computer Vision and Pattern Recognition (CVPR), 2015 F. Pittaluga and S. J. Koppal

C08 Data Fusion for a Vision-Radiological System for Source Tracking and Discovery Advancements in Nuclear Instrumentation Measurement Methods and their Applic., 2015 A. Enqvist and S. J. Koppal

C07 MEMS mirrors submerged in liquid for wide-angle scanning International Conference on Solid-State Sensors, Actuators and Microsystems, 2015 X. Zhang, R. Zhang, S. J. Koppal, E. Butler, X. Cheng and H. Xie

 ${\bf C06}$ Wide-angle micro sensors for vision on a tight budget Conference on Computer Vision and Pattern Recognition (CVPR), 2011.

S. J. Koppal, I. Gkioulekas, T. Zickler and G. Barrows

C05 Shadow cameras: Reciprocal views from illumination masks International Conference on Computer Vision (ICCV), 2009.

S. J. Koppal and S. G. Narasimhan

 ${\bf C04}$ Temporal dithering of illumination for fast active vision European Conference on Computer Vision (ECCV), 2008.

S. G. Narasimhan, S. J. Koppal and S. Yamazaki

C03 Novel depth cues from uncalibrated near-field lighting International Conference on Computer Vision (ICCV), 2007.

S. J. Koppal and S. G. Narasimhan

C02 Clustering appearance for scene analysis Conference on Computer Vision and Pattern Recognition (CVPR), 2006.

S. J. Koppal and S. G. Narasimhan

C01 Structured light from scattering media
International Conference on Computer Vision (ICCV), 2005.
S. G. Narasimhan, S. K. Nayar, B. Sun and S. J. Koppal

Book chapters

BC02 Koppal S.J. (2014) Lambertian Reflectance. In: Ikeuchi K. (eds) Computer Vision. Springer, Boston, MA

BC01 Koppal S.J. (2014) Diffuse Reflectance. In: Ikeuchi K. (eds) Computer Vision. Springer, Boston, MA

Workshops and other publications

W04 A low-power structured light sensor for outdoor scene reconstruction and dominant material identification

International Workshop on Projector-Camera Systems, 2012

C. Mertz, S. J. Koppal, S. Sia and S. G. Narasimhan

W03 Illustrating motion through DLP Photography PROCAMS, 2008

S. J. Koppal and S. G. Narasimhan

W02 Leveraging Gaze Data for Segmentation and Effects on Comics ACM Symposium on Applied Perception Poster, 2016 I. Thirunarayanan, S. J. Koppal, J. Shea and E. Jain

W01 Taylor Series of Appearance Functions CMU-Robotics Institute Technical report, 2006

S. J. Koppal, A. Datta, S. G. Narasimhan and K. Nishino

PATENTS

P07 S. J. Koppal, S.B. Kang, C.L. Zitnick, M.F. Cohen, and B.K. Ressler Stereo movie editing, US Patent 8,330,802

P06 T. Zickler, **S. J. Koppal**, G. L. Barrows and I. Gkioulekas Optical micro-sensor, US Patent 9,176,263

P05 S. J. Koppal

Depth sensor data with real-time processing of scene sensor data, US Patent 9,767, 545

P04 S. J. Koppal

Time-of-Flight (TOF) Assisted Structured Light Imaging , US Patent Application US20150062558A1 (Pending)

P03 S. J. Koppal

Controlling Image Focus in Real-Time Using Gestures and Depth Sensor Data, US Patent Application US20150022649A1 (Pending)

P02 S. J. Koppal and F. Pittaluga

Optical privatizing device, system and method of use, US Patent Application US20180063509A1 (Pending)

P01 Huikai Xie, **S. J. Koppal**, Xiaoyang Zhang, Liang Zhou and Can Duan Endoscopic oct probes with immersed mems mirrors, WO Application WO2018023010A1 (Pending)

FUNDING AWARDS (TOTAL $\sim \$2M$, PI SHARE $\sim \$1M$)

 ${\bf F05}$ Directionally Controlled Time-of-Flight Sensors: Algorithms, Optical and Imaging (2018-2021)

Office of Naval Research (ONR) N00014-18-1-2663

Total $\sim $780,000 \text{ PI share} \sim $390,000$

F04 Novel Micro-LIDAR design and sensing algorithms for flapping-wing Micro-aerial Vehicle (2015-2019)

National Science Foundation (NSF) 1514154

Total $\sim $400,000 \text{ PI share} \sim $200,000$

 ${\bf F03}$ Radiological Source Detection and Tracking Based on Multi-Sensor Data Fusion (2014-18)

Department of Homeland Security (DHS) 2014-DN-077-ARL083-03

Total $\sim $890,000$, co-PI share $\sim $460,000$

F02 Wide-angle optics for micro-LIDAR sensor (2018-2019)

MIST Center Award, Total \sim \$50000, PI share \sim \$25000

F01 Texas Instruments Embedded Processing University Funding Award (2013)

TEACHING

T02 Computational Photography, Fall 2014-present

Latest rating 4.3 for undergraduates and 4.5 for graduate students

I developed this Computational Photography course from scratch at UF, and which received its official course numbers recently (EEL 4403/5406). This course contains hands-on lab activity, where simple but powerful computational photography techniques were implemented in-lab, using just cellphone cameras and a few support structures (such as optical masks or a tripod). To inspire students further, the support structures were also designed and built by the students using 3D printers.

T01 Signals and Systems, Spring 2015-present

Latest rating 3.8 for undergraduates

EEL 3135 (Signals and Systems) is a core course for an undergraduate degree in Electrical and Computer Engineering at UF. The goal of the course is to garner a practice-based understanding of time-varying information (signals) and the software/circuits needed to process these (systems). I exploit the flipped nature of the class to help students develop abstract complex number processing skills, so that future courses that delve into the theory of signals and systems are accessible.

STUDENTS

Ph.D. Students

D04 Xiaoyang Zhang, graduated 2016 (co-advised)

Thesis: Robust Electrothermally Actuated Scanner for Fiberoptic Endoscopic Imaging and Wide-angle Optics

Magic Leap (first appointment)

D03 Francesco Pittaluga, expected May 2019

Thesis proposed: Privacy Preserving Computational Cameras

2018 Microsoft Research Dissertation Awardee

D02 Kristofer Henderson, expected May 2020

Thesis proposed: Lightweight Sensor Fusion using Radial Trajectories

D01 Justin Folden, expected May 2023

Thesis committees

Richard Al-Bayaty Electrical and Computer Engineering

Manu Chandran Electrical and Computer Engineering

Pratik Brahma Electrical and Computer Engineering

Chiranjib Sur Computer Engineering

Kelsey Stadniki Nuclear Engineering Sciences

Xiaohui Huang Computer Science

Inchul Choi Computer Science

Xianjin Dai Biomedical Engineering

Paul Johns Nuclear Engineering Science

AWARDS

Best Student Paper Award (NEMS 2018)

Best Student Paper Award (ECCV 2016)

Outstanding Reviewer Award (ECCV 2016)

USC Computer Science Award for Outstanding Achievement (2003)

USC Trustee Scholarship (full tuition) (1999-2003)

USC Undergraduate Engineering Research Award (1999-2003)

SERVICE

S04 Area chair for Computer Vision and Pattern Recognition (CVPR) 2019

 ${f S03}$ Co-chair for Cameras and Computational Displays (CCD) 2018 workshop held in conjunction with CVPR 2018

S02 Posters/Demos co-chair for International Conference on Computational Photography (ICCP) 2018

S01 Reviewer for Scholarly Journals/Conferences

IEEE Pattern Analysis and Machine Intelligence (PAMI), IEEE Transactions on Image Processing (TIP), International Journal on Computer Vision (IJCV), Computer Vision and Pattern Recognition (CVPR), European Conference on Computer Vision (ECCV), International Conference on Computer Vision (ICCV), International Conference on Computational Photography (ICCP)

INVITED TALKS

IT 11 Optics and Sensing for Small Vision Platforms FAU I-SENSE Boca Raton, FL (Oct 2018)

IT 10 Toward Miniature Computer Vision Sensors OSA Imaging Systems and Applications Orlando, FL (June 2018)

IT 09 Small Vision Sensors for Phenomics Phenome Tucson, AZ (February 2018)

IT 08 Towards Privacy Preserving Cameras ASU SENSIP

Phoenix, AZ (2018)

IT 07 Wide-FOV Sensing & Optical Processing for Small Vision Applications OSA Incubator on Small Eyes and Smart Minds Washington, DC (October 2017)

IT 06 Towards Privacy Preserving Cameras IRISA-Rennes Rennes, France (2017)

IT 05 Towards Privacy Preserving Cameras Technicolor R&D Labs Rennes, France (2017)

IT 04 Towards Privacy Preserving Cameras INRIA-Bordeaux/LPN2 Bordeaux, France (2017)

IT 03 Towards Privacy Preserving Cameras UCF CRCV Orlando, FL (2017)

IT 02 Towards Micro Vision Sensors UCF CREOL Orlando, FL (2017)

IT 01 Privacy Preserving Sensors University of Miami CSD Miami, FL (2015)

MEDIA COVERAGE

 \mathbf{MC} 04 "RoboBees Can Fly and Swim. What's Next? Laser Vision" Smithsonian Magazine

MC 03 "RoboBee Lidar Useful for Robocars?" IEEE Spectrum

MC 02 "'RoboBees' with Laser Eyes Could Locate Disaster Victims" NBC News

 \mathbf{MC} 01 "Scientists Are Using Lasers to Teach RoboBees to See" Smithsonian Magazine

OTHER INFORMATION

Languages: English, Hindi, Kannada

Citizenship: India

Immigration Status: U.S. Permanent Resident

Lab Website: focus.ece.ufl.edu